

# AS5030

8 BIT PROGRAMMABLE HIGH SPEED  
MAGNETIC ROTARY ENCODER

## DEMOBOARD OPERATION MANUAL

### 1 General Description

The AS5030 is a contactless magnetic rotary encoder for accurate angular measurement over a full turn of 360°. It is a system-on-chip, combining integrated Hall elements, analog front end and digital signal processing in a single device.

To measure the angle, only a simple two-pole magnet, rotating over the center of the chip is required.

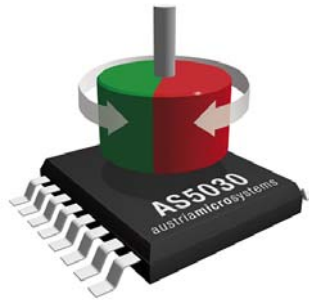
The absolute angle measurement provides instant indication of the magnet's angular position with a resolution of 8 bit = 256 positions per revolution. This digital data is available as a serial bit stream and as a PWM signal.

In addition to the angle information, the strength of the magnetic field is also available as a 6-bit code.

Data transmission can be configured for 1-wire (PWM), 2-wires (CLK, DIO) or 3-wires (CLK, DIO, CS).

A software programmable (OTP) zero position simplifies assembly as the zero position of the magnet does not need to be mechanically aligned.

A Power Down Mode together with fast startup- and measurement cycles allows for very low average power consumption and makes the AS5030 also suitable for battery operated equipment.



### The AS5030 Demoboard

The AS5030 demoboard measures the angle of a diametral magnet turning over the AS5030 sensor. It is controlled by a built-in microcontroller and shows the result on the LCD display or on the PC GUI via the USB interface.

The board is powered from the USB plug if it is connected to a PC, or from an external power supply on the DC Jack (>7.5V) if the board works in stand alone mode without any PC. The angle and AGC values are displayed on the LCD screen in both modes.

Dimensions of the demo board: 77mm x 84mm (3.03 x 3.30 inch).



Figure 1: AS5030 demoboard, TOP side

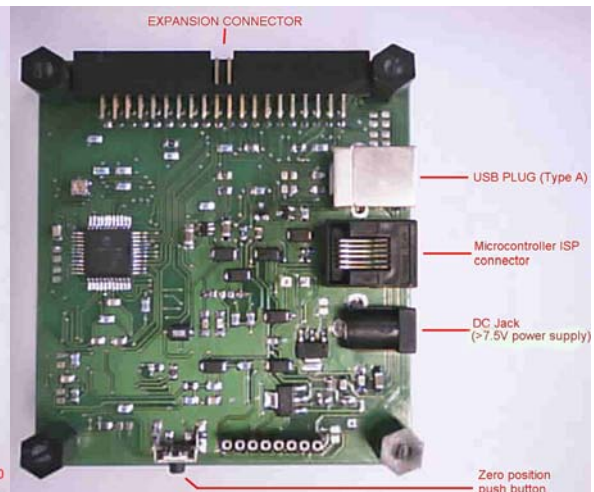


Figure 2: AS5030 demoboard, BOTTOM side

## 2 AS5030 Software

### 2.1 Getting Started

This software allows you to become familiar with the principle of the AS5030 sensor. In order to get started, you need:

- The AS5030 Demo Software installer, downloadable on the Austriamicrosystems website
- Win-XP® or Windows Vista® operating system
- one free USB slot on your PC to connect the demoboard

### 2.2 Installing the Software

The installation process consists of three steps:

- Unzip the Demoboard software installation *AS5030\_DemoBoard\_Software\_Setup.zip* in any local directory
- Execute the .exe setup file
- Follow the instructions on the screen

The demoboard and the software don't need any other files or drivers to be installed on the computer.

### 2.3 Software Usage

Before starting the software the board needs to be connected to the PC.  
After starting the software, two modes can be selected: *SSI-Readout* and *OTP*.

For both modes, the following functions are present:



Figure 3: USB Connect

#### USB:

*Connected/No connection.* If the demoboard is correctly connected to the PC, the software should find immediately the demo board.

#### Onboard / External:

Switch the actual AS5030 sensor from the on-board one (by default), to an external AS5030 connected on the "external AS5030 header" (see Figure 1).

## 2.4 SSI-Readout

After starting the demo software and selecting the "SSI-Readout" tab, the magnet angle, AGC value, PWM out value are displayed (see Figure 4).

For a correct reading of the magnet angle, the airgap between the AS5030 top side and the magnet should be chosen that the  $0 < AGC < 63$ . If the AGC value reaches 63, the ALARM LED will blink to indicate that the magnet is too far away from the sensor, and the measurement is not accurate or not valid.

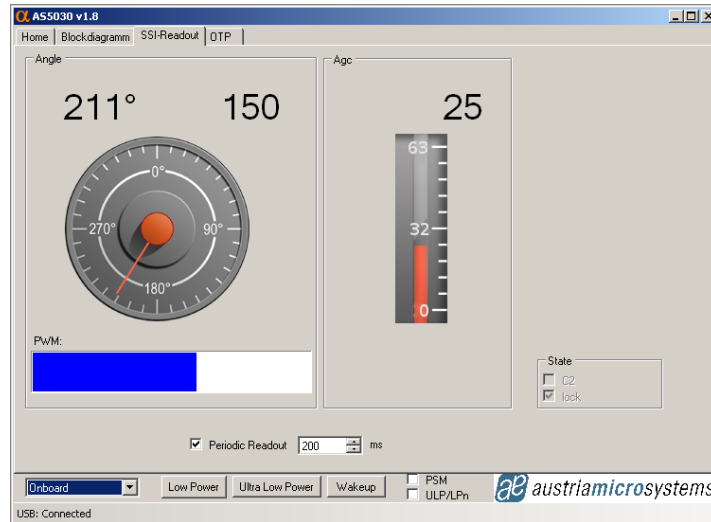


Figure 4: SSI-Readout tab

### Periodic Readout:

By unchecking this option, the angle and AGC values are not read anymore, and the displayed value keep their last state during the normal readout.

The read period can be adjusted between 50ms and 1s (default 200ms), to have more or less reactivity.

### State:

Displays the state of the C2 pin on the selected AS5030. By default C2 = 0 (three wires mode).

The Lock indicator is the state of the lock bit in the serial stream. This bit should be always enabled.

### Low Power / Ultra Low Power / Wakeup:

Function not yet implemented

## 2.5 OTP

The "OTP" tab, displays the OTP configuration bit of the selected AS5030 sensor.

- In Onboard mode, the configuration bits can be temporary changed (access to the *Read* and *Write* functions only). After a new power up, the configuration bits are set back to their default state.
- In External mode, the AS5030 can be temporary configured, and can be permanently programmed too. The *Read*, *Write* and *Prog* functions are available.

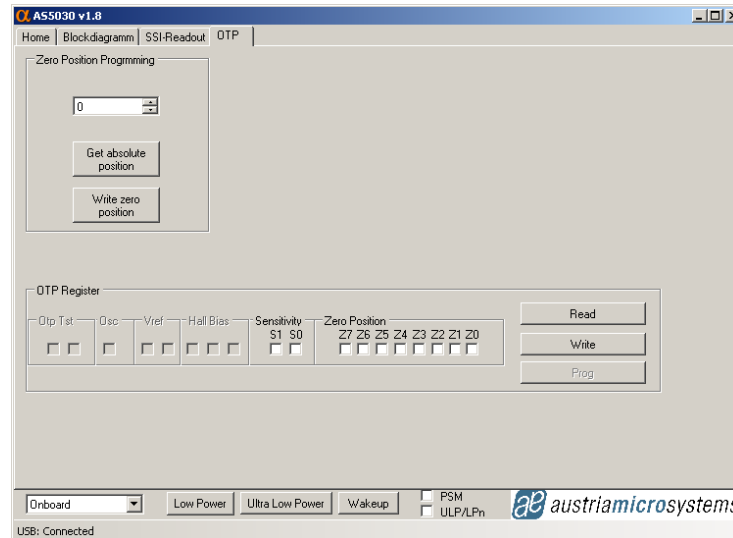


Figure 5: OTP tab

### Zero Position Programming:

The Zero Position Programming tool is used to assign a zero value to a defined mechanical position.

Move the magnet to a desired reference position, which is the mechanical 0°.

Click on "Get absolute position". The actual angle seen on the sensor side is displayed in decimal and binary (Z7..0 bits).

Click on "Write zero position". The bits Z7..0 are written to the *Zero Position* register of the AS5030. Now the actual mechanical angle is the 0° angle on the AS5030 side.

This value can be permanently fused on an external AS5030 sensor by clicking on *Prog*.

### OTP registers:

In *On-board* mode, the OTP registers can't be permanently fused.

- *Read*: Reads back the OTP configuration registers of the selected sensor.
- *Write*: Writes the configuration bits as represented in the checkboxes to the selected AS5030. Those bits won't be permanently written, and will be lost if the sensor is powered down.
- *Prog* (external mode only): After having written the configuration bits to the AS5030, those bits can be permanently fused by clicking on *Prog*. After a new power up of the device, this new configuration is enabled.

### 3 AS5030 Demoboard hardware

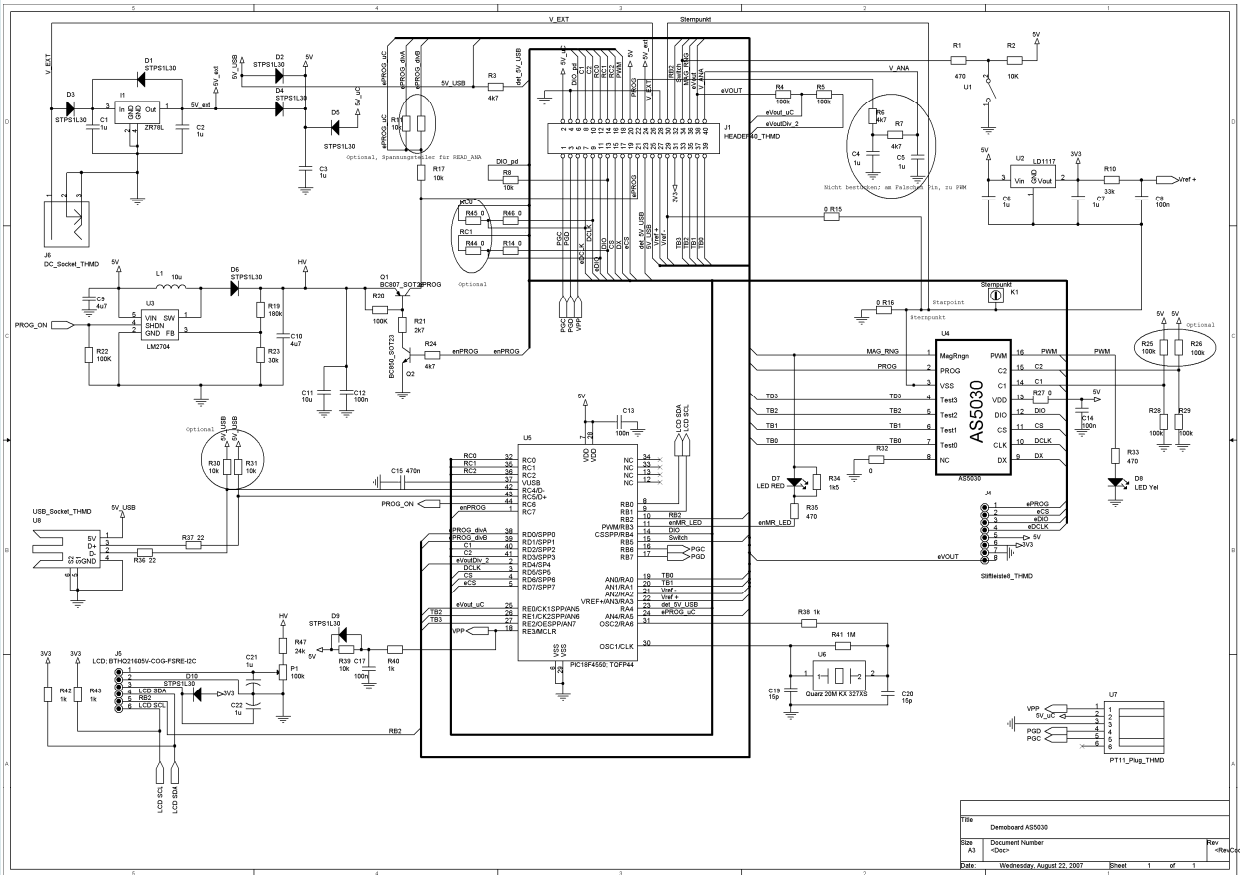


Figure 6: AS5030\_DB\_1.3 Demoboard schematics

#### 3.1.1 Power supply

The demoboard is powered directly from the USB plug of a PC or from an external DC power supply (>7.5V, 100mA) connected on the DC jack J6 and regulated through a 5V voltage regulator (I1, ZR78L05).

The programming high voltage (8.5V) for the external AS5030 is generated directly from the 5V source through a DC/DC step-up converter U3. This source is used for the LCD power supply as well, for the contrast control through the P1 potentiometer.

The U2 voltage regulator is necessary for the 3.3V LCD power supply.

#### 3.1.2 AS5030 Encoder

The AS5030 (U4) is running with the 5V source. The resistor R27 (0R) can be removed if the user wants to use his own power supply for his own tests.

The SSI serial interface (DIO, CS, DCLK) is controlled by the microcontroller U5.

The LED D7 is directly connected to the AS5030 on the MagRngn pin on one side, and on U5 for the other side to make it blinking if MagRngn = 5V (magnet too far away).

The PWM LED is directly connected on the PWM signal of U4.

The Test3..0 signals are connected to U5 but are not used.

#### 3.1.3 Microcontroller

The microcontroller PIC 18F4550 (U5) from Microchip includes an on-chip USB interface.

The U1 switch enables the bootloader mode of the microcontroller, if pressed during power up.

In normal mode, pressing the switch makes the microcontroller writing the zero position value into the active AS5030.

The connector U7 is used for ISP programming of the microcontroller only.

### 3.1.4 J4 connector for external AS5030

An external AS5030 device can be wired to this connector. It allows the user to test his own board, and/or fuse the configuration bits for the mass production.

- Pin 1: ePROG.  
Is the 8.5V source for fusing. The high voltage is switched only during the programming phase.
- Pin 2: eCS  
Is an independent CS signal provided by the microcontroller, only for the external sensor
- Pin 3: eDIO  
Is the same signal as DIO used for the on board sensor. Both are connected through the R14 resistor (0R). Only one sensor, on-board or external, can be selected at the same time with the CS and eCS signal.
- Pin 4: eDCLK  
Is the same signal as DCLK used for the on board sensor. Both are connected through the R46 resistor (0R). Only one sensor, on-board or external, can be selected at the same time with the CS and eCS signal.
- Pin 5: 5V  
Is the power supply of the external sensor
- Pin 6: 3.3V  
Not used
- Pin 7: VSS
- Pin 8: eVOU  
Analog input. Not used

## 4 Troubleshooting

When operating the demo board and software it is advisable to proceed as:

- Running the demo software

Before starting the demo software the demo board needs to be connected to the USB port of the PC.

1. Connect to the USB port.
2. Start the software.

- Closing the demo software

After finishing the work with the demo board the software needs to be closed before disconnecting the demo board.

1. Close the software.
2. Disconnect from the USB port.

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## Contact Information

### Headquarters

austriamicrosystems AG

A-8141 Schloss Premstaetten, Austria

Tel: +43 (0) 3136 500 0

Fax: +43 (0) 3136 525 01

For Sales Offices, Distributors and Representatives, please visit:

<http://www.austriamicrosystems.com>