

# DP83TD510E Ultra Low Power 802.3cg 10Base-T1L 10M Single Pair Ethernet PHY

### 1 Features

- Long cable reach
  - 2000 meters+ with 1-V p2p
  - 2000 meters+ with 2.4-V p2p
- Ultra-low power
  - 38 mW for 1-V p2p mode
  - 82 mW for 2.4-V p2p mode
- Compliant to IEEE 802.3cg 10Base-T1L
- IEC 61000-4-4 EFT ±4 KV at 5 KHz, 100 KHz
- IEC61000-4-5 surge ±2KV at 1,2/50us, 8/20us
- IEC 61000-4-2 contact discharge ±4 KV, ±8 KV air discharge
- CISPR22 radiated emission class B
- External MDI terminations for intrinsic safety
- MAC interface:
- MII mode
- RMII master/slave mode
- RGMII mode
- RMII master low-power 5-MHz mode
- RMII back-2-back mode for range extender
- Power supply
  - single supply operations from 3.3 V
  - dual supply operations for lowest power dissipation
- I/O voltages: 1.8 V, 2.5 V or 3.3 V
- Diagnostics tool kit
  - cable open and short detection
  - signal quality indicator (SQI) for cable \_ degradation
  - active link cable diagnostics (ALCD)
- Clock output: 25 MHz, 50 MHz (RMII master)
- ±6-kV HBM ESD protection on MDI pins
- Operating temperature range: -40°C to 105°C
- Package: 5 mm x 5 mm, 32 pin with 0.5 mm pitch

# 2 Applications

- Process automation
  - Field transmitters and switches
- **Building automation**
- HVAC controllers
- Elevators and escalators
- Fire safety
- Factory automation and control

# **3 Description**

The DP83TD510E is an ultra-low power Ethernet physical layer transceiver compliant with the IEEE 802.3cg 10Base-T1L specification. The PHY has very low noise coupled receiver architecture enabling long cable reach and very low power dissipation. The DP83TD510E has external MDI termination to support intrinsic safety requirements. It interfaces with MAC layer through MII, Reduced MII (RMII), RGMII, and RMII low power 5-MHz master mode. It also supports RMII back-to-back mode for applications that require cable reach extension beyond 2000 meters. It supports a 25MHz reference clock output to clock other modules on the system. The DP83TD510E offers integrated cable diagnostic tools; built-in selftest, and loopback capabilities for ease of design or debug.

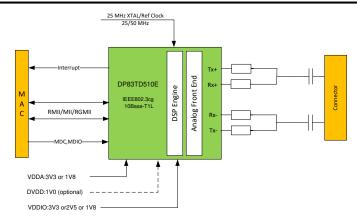
#### **Device Information**

PART NUMBER <sup>(1)</sup>	PACKAGE	BODY SIZE (NOM)
DP83TD510E	QFN (32)	5.00 mm × 5.00 mm

For all available packages, see the orderable addendum at (1)the end of the data sheet.







DP83TD510E Application Diagram



# **Table of Contents**

1 Features	1
2 Applications	
3 Description	
4 Revision History	3
5 Pin Configuration and Functions	4
Pin Functions	<mark>5</mark>
6 Specifications	<mark>8</mark>
6.1 Absolute Maximum Ratings	<mark>8</mark>
6.2 ESD Ratings	8
6.3 Recommended Operating Conditions	8
6.4 Thermal Information	9
6.5 Electrical Characteristics	9
6.6 Timing Requirements	14
6.7 Timing Diagrams	17
7 Detailed Description	20
7.1 Overview	20
7.2 Functional Block Diagram	
7.3 Feature Description	21
7.4 Device Functional Modes	32

34
34
35
70
70
70
74
76
79
79
79
79
79
79
80

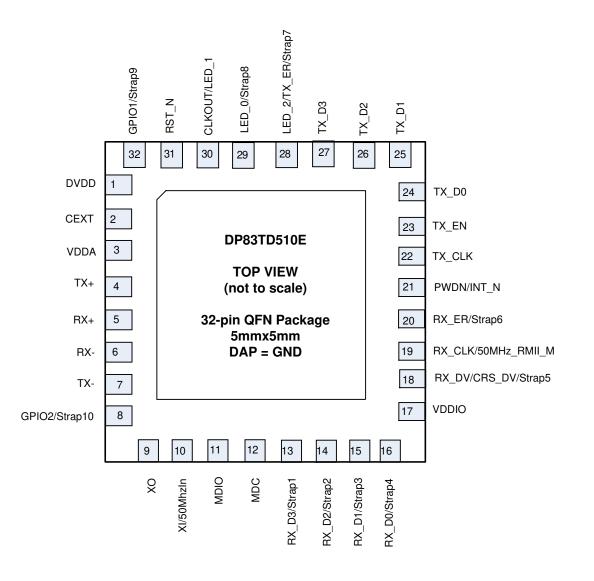
# **4 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Cł	hanges from Revision B (October 2020) to Revision C (December 2020)	Page
•	Changed maketing status from Advance Information to initial release	1



# **5** Pin Configuration and Functions



Copyright © 2020, Texas Instruments Incorporated

Figure 5-1. RMQ Package 32-Pin VQFN Top View



# **Pin Functions**

PIN		TYPE	DESCRIPTION			
NAME	NO	-				
DVDD	1	A	<ul> <li>Digital supply 1.0 V</li> <li>For single-supply operation: Short this pin with CEXT (Pin 2)</li> <li>Optional (dual-supply operation): Connect external 1.0 V to achieve lowest power</li> </ul>			
			Refer to Power Connection Diagram in Application section			
CEXT	2	A	<ul> <li>External capacitor for internal LDO</li> <li>For single-supply operation: Connect 0.01- μF capacitor and short it with pin 1</li> <li>For dual-supply operation, leave unconnected</li> </ul>			
			Refer to Power Connection Diagram in Application section			
VDDA	3	A	<ul> <li>Supply 3.3 V to support both 2.4-V p2p and 1-V p2p mode.</li> <li>Supply 1.8 V to support only 1-V p2p mode.</li> <li>Supplied voltage will be reflected in bit 13 of auto negotiation base page as capability to support 2.4-V p2p or 1-V p2p.</li> <li>0x20E, bit 13 = 1 when 3.3 V is selected.</li> <li>0x20E, bit 13 = 0 when 1.8 V is selected.</li> <li>Ensure the Strap7 "Reach Selection" strap is selected appropriately to request the output voltage level in the auto negotiation page.</li> </ul>			
TX+	4	A	TX+, TX- : Differential Transmit Output (PMD): These differential outputs are configured to 2.4-V p2p or 1-V p2p mode based on configuration chosen for PHY and auto negotiation with Link Partner.			
RX+	5	A	RX+, RX- : These differential inputs are automatically configured to accept 2.4-V p2p or 1-V			
RX-	6	A	p2p mode based on configuration chosen for PHY.			
TX-	7	A	TX+, TX- : Differential Transmit Output (PMD): These differential outputs are configured to 2.4-V p2p or 1-V p2p mode based on configuration chosen for PHY and auto negotiation with Link Partner.			
GPIO2	8	Strap	GPIO: This pin can be configured for multiple configuration thru register configuration. It has mandatory PU or PD strap. Refer to Straps sections for details.			
хо	9	A	Crystal Output: Reference Clock output. XO pin is used for crystal only. This pin should be left floating when a CMOS-level oscillator is connected to XI.			
XI/50MHzIn	10	A	Crystal / Oscillator Input Clock MII, RMII master mode: 25-MHz ±50 ppm-tolerance crystal or oscillator clock RMII slave mode: 50-MHz ±50 ppm-tolerance CMOS-level oscillator clock			
MDIO	11		Management Data I/O: Bi-directional management data signal that may be source by the management station or the PHY. This pin requires an external pull of $2.2k\Omega - 4.0 k\Omega$ .			
MDC	12		Management Data Clock: Synchronous clock to the MDIO serial management input/output data. This clock may be asynchronous to the MAC transmit and receive clocks. The maximum clock rate is 1.75 MHz.			
RX_D3	13	Strap	Receive Data: Symbols received on the cable are decoded and presented on these pins			
RX_D2	14	Strap	synchronous to the rising edge of RX_CLK. They contain valid data when RX_DV is asserted. A nibble RX_D[3:0] is received in MII modes. 2-bits RX_D[1:0] is received in RMII mode.			
RX_D1	15	Strap				
RX_D0	16	Strap				
VDDIO	17	Power	I/O Supply : 3.3 V/2.5 V/1.8 V. For decoupling capacitor requirements, refer to Power Connection Diagram in Application section.			
RX_DV/ CRS_DV	18	Strap	Receive Data Valid: This pin indicates valid data is present on the RX_D[3:0] for MII mode and on RX_D[1:0] for RMII mode. In RMII mode, this pin acts as CRS_DV and combines the RMII arrier and Receive Data Valid indications. This pin can be configured to RX_DV to enable RMII repeater mode using strap or register configuration. RGMII mode: RGMII Receive Control: RX_CTRL combines receive data valid and receive error signals. RX_DV is presented on the rising edge of RX_CLK and RX_ER on the falling edge of RX_CLK.			

#### **DP83TD510E**

SNLS656C - AUGUST 2020 - REVISED DECEMBER 2020



DUMPRMI         19         not used and remains Input/PD.           RGMII Receive Clock: RGMIR Receive Clock provides a 2.5-MHz reference clock for 10-Mt speed, which is derived from the receive data stream.           RX_ER         20         Strap         Receive Error: This pin indicates that an error symbol has been detected within a received packet in both MII and RMII mode. INII mode, RX_ER is asserted high synchronously to the rising edge of the reference clock. RX_ER is asserted high prochronously to the rising edge of the reference clock. RX_ER is asserted high for every reception error, including errors during idfe.           PWDN/INT         21         Power Down(Default)/Interrupt: The default function of this pin is power down. Register access is required to configure this pin as an interrupt condition occurs. The pin has an optication set to configure that is pin places the device in power down mode.           PWDN/INT         21         MII Transmit Clock: MII Transmit Clock provides a 2.5-MHz reference clock for 10-Mbps speed. This clock must be 2.5-MHz.           TX_CLK         22         MII Transmit Clock: MII transmit Clock provides a 2.5-MHz.           TX_EN         23         Transmit Clock: The clock is sourced from the MAC layer to the PHY. When operatin at 10-Mbps speed, this clock must be 2.5-MHz.           TX_EN         23         Transmit Clock: The clock is sourced from the MAC layer to the PHY. When operatin at 10-Mbps speed, this clock must be 2.5-MHz.           TX_EN         23         Transmit Clock: The clock is sourced from the MAC layer to the PHY. When operatin at 10-Mbps speed, this clock must be	PIN		TYPE	DESCRIPTION			
RX_CLK/ 50MHz_FMII         19         speed, which is derived from the received data stream. In RMII master mode, this provides 50-MHz reference clock. In RMII slave mode, this prin is not used and remains input/PD. RGMII Receive Clock RGMI Receive Clock provides a 2.5-MHz reference clock for 10-Mb speed, which is derived from the receive data stream.           RX_ER         20         Strap         Receive Error. This pin indicates that an error symbol has been detected within a received data stream.           RX_ER         20         Strap         Receive Error. This pin indicates that an error symbol has been detected within a received data other defence clock. RX_ER is asserted high synchronously to the rising edge of the reference clock. RX_ER is asserted high synchronously to the rising edge of the reference clock. RX_ER is asserted high synchronously to the rising edge of the reference clock. RX_ER is asserted high synchronously to the rising edge of the reference clock. RX_ER is asserted high synchronously to the rising edge of the reference clock. RX_ER is asserted high synchronously to the rising edge of the reference clock. RX_ER is asserted high synchronously to the rising edge of the reference clock. RX_ER is asserted high synchronously to rising and this pin places the device in power down mode. When this pin is confluence as interrupt pin, this pin is asserted low when an interrupt condition occurs. The pin has an op ediral output with a weak internal pullup (9.5 kQ). Some applications may require an extern PU resistor.           TX_CLK         22         MII Transmit Clock: MII Transmit Clock is sourced from the MAC layer to the PHY. When operatin at 10-Mbps speed, this clock must be 2.5-MHz.           TX_EN         23         Transmit Enable: TX_EN is presented on	NAME	NO	-				
RX_ER         20         Strap         packet in both MII and RMII mode. In MIII mode, RX_ER is asserted high synchronously to the rising edge of RX_CLK. In RMII mode, RX_ER is asserted high for every reception error, including edge of the reference clock. RX_ERR is asserted high for every reception error, including errors during table.           PWDN/INT         21         Power Down(Default)/Interrupt: The default function of this pin is power down. Register access is required to configure this pin as an interrupt. In power down function, an active to signal on this pin places the device in power down mode. When this pin is configured as an interrupt pin, this pin is asserted low when an interrupt condition occurs. The pin has a top drain output with a weak internal pullup (9.5 kΩ). Some applications may require an external PU resistor.           TX_CLK         22         MIII transmit Clock: MII Transmit Clock provides a 2.5-MHz reference clock for 10-Mbps speed. Unused in RMII mode.           TX_EN         23         Transmit Enable: TX_EN is presented on the rising edge of the TX_CLK. TX_EN indicates presence of valid data inputs on TX_D13.01 in MIII mode and on TX_D11.01 in RMIII mode.           TX_EN         23         Transmit Enable: TX_EN is presented on the rising edge of TX_CLK. TX_EN in indicates the ransmit data nibble received from the AMC is synchronous to to TX_CLK. TX_EN is presented on the rising edge of TX_CLK. TX_EN indicates TX_D1           TX_D0         24         Transmit Enable: TX_CTX_CTRL combines transmit enable and transmit error signals. TX_EN is presented on the rising edge of TX_CLK and TX_ER on the failing edge of TX_CLK. In RMII Made: TX_CLK.           TX_D0         24	50MHz_RMII	19		speed, which is derived from the received data stream. In RMII master mode, this provides 50-MHz reference clock. In RMII slave mode, this pin is not used and remains Input/PD. RGMII Receive Clock: RGMII Receive Clock provides a 2.5-MHz reference clock for 10-Mbps			
PWDN/INT         21         access is required to configure this pin as an interrupt. In power down function, an active lo signal on this pin places the device in power down mode. When this pin is configured as an interrupt pin, this pin is asserted low when an interrupt condition occurs. The pin has an opy drain output with a weak internal pullup (9.5 kΩ). Some applications may require an externa PU resistor.           TX_CLK         22         MII Transmit Clock: MII Transmit Clock provides a 2.5-MHz reference clock for 10-Mbps speed. Unused in RMII mode. RGMII transmit Clock: The clock is sourced from the MAC layer to the PHY. When operatin at 10-Mbps speed, this clock must be 2.5-MHz.           TX_EN         23         Transmit Enable: TX_EN is presented on the rising edge of the TX_CLK. TX_EN indicates presence of valid data inputs on TX_D[3:0] in MII mode and on TX_D[1:0] in RMII mode. TX_EN is an active high signal. RGMII Transmit Conto: TX_CTRL combines transmit enable and transmit error signals. TX_EN is presented on the rising edge of TX_CLK and TX_ER on the falling edge of TX_CLK.           TX_D0         24         Transmit Data: In MII mode, the transmit data nibble received from the MAC is synchronous to CLKOUT50M output of the device           TX_D2         26         In RMII Slave mode, TX_D[0,1] are synchronous to CLKOUT TX_DR           LED_2/         28         Strap           This pin acts as LED_2 by default. It can be configured as GPIO or TX_ER as well. The LE is ON when link is negotiated for 10M (short reach). LED remains OFF otherwise.           LED_0         29         Strap         This pin acts as LEO_2 by default. It can beconfigure as default to clo	RX_ER	20	Strap	packet in both MII and RMII mode. In MII mode, RX_ER is asserted high synchronously to the rising edge of RX_CLK. In RMII mode, RX_ER is asserted high synchronously to the rising edge of the reference clock. RX_ERR is asserted high for every reception error, including errors during Idle.			
TX_CLK22speed. Unused in RMII mode. RGMII Transmit Clock: The clock is sourced from the MAC layer to the PHY. When operatin at 10-Mbps speed, this clock must be 2.5-MHz.TX_EN23Transmit Enable: TX_EN is presented on the rising edge of the TX_CLK. TX_EN indicates presence of valid data inputs on TX_D[3:0] in MII mode and on TX_D[1:0] in RMII mode. TX_EN is an active high signal. RGMII Transmit Control: TX_CTRL combines transmit enable and transmit error signals. TX_CLK.TX_D024Transmit Data: In MII mode, the transmit data nibble received from the MAC is synchronous to the rising edge of TX_CLK. and TX_ER on the falling edge of TX_CLK.TX_D125CLKOUT50M output of the device In RMII Slave mode, TX_D[0,1] are synchronous to CLKOUT50M output of the device In RMII Slave mode, TX_D[0,1] are synchronous to rising edge of Ref clockTX_D226In RMII Slave mode, TX_D[0,1] are synchronous to rising edge of Ref clockTX_LR27EED_2/ IS ON when link is negotiated for 10M (short reach). LED remains OFF otherwise.LED_029StrapLED : Activity Indication LED indicates transmit and receive activity in addition to the status the link. The LED is ON when link is good. The LED blinks when the transmitter or receiver active. This pin can also act as GPIO using register configuration.CLKOUT/ LED_130This pin can also act as GPIO using strap or register configuration.RST_N31areset process to occur. Initiation of reset causes strap pins to be re-scanned and resets a reset process to occur. Initiation of reset causes strap pins to be re-scanned and resets a	PWDN/INT	21		access is required to configure this pin as an interrupt. In power down function, an active low signal on this pin places the device in power down mode. When this pin is configured as an interrupt pin, this pin is asserted low when an interrupt condition occurs. The pin has an oper drain output with a weak internal pullup $(9.5 \text{ k}\Omega)$ . Some applications may require an external			
TX_EN23presence of valid data inputs on TX_D[3:0] in MII mode and on TX_D[1:0] in RMII mode. TX_EN is an active high signal. RGMII Transmit Control: TX_CTRL combines transmit enable and transmit error signals. TX_EN is presented on the rising edge of TX_CLK and TX_ER on the falling edge of TX_CLK.TX_D024Transmit Data: In MII mode, the transmit data nibble received from the MAC is synchronous to the rising edge of TX_CLK. In RMII Master mode, TX_D[0,1] are synchronous to CLKOUT50M output of the device In RMII Slave mode, TX_D[0,1] are synchronous to CLKOUT50M output of the device In RMII Slave mode, TX_D[0,1] are synchronous to CLKOUT50M output of the device In RMII Slave mode, TX_D[0,1] are synchronous to rising edge of Ref clockTX_ER28StrapThis pin acts as LED_2 by default. It can be configured as GPIO or TX_ER as well. The LE is ON when link is negotiated for 10M (short reach). LED remains OFF otherwise.LED_229StrapLED : Activity Indication LED indicates transmit and receive activity in addition to the status the link. The LED is ON when link is good. The LED blinks when the transmitter or receiver active. This pin can also act as GPIO using strap or register configuration.CLKOUT/ LED_130This pin provides Reference CLKOUT of 25 MHz as default to clock other module on the 	TX_CLK	22		speed. Unused in RMII mode. RGMII Transmit Clock: The clock is sourced from the MAC layer to the PHY. When operating			
TX_D125to the rising edge of TX_CLK. In RMII Master mode, TX_D[0,1] are synchronous to CLKOUT50M output of the device In RMII Slave mode, TX_D[0,1] are synchronous to rising edge of Ref clockTX_D226In RMII Slave mode, TX_D[0,1] are synchronous to rising edge of Ref clockTX_D327Image: transmitter content of the device In RMII Slave mode, TX_D[0,1] are synchronous to rising edge of TX_CLK.LED_2/ TX_ER28StrapThis pin acts as LED_2 by default. It can be configured as GPIO or TX_ER as well. The LE is ON when link is negotiated for 10M (short reach). LED remains OFF otherwise.LED_029StrapLED : Activity Indication LED indicates transmit and receive activity in addition to the status the link. The LED is ON when link is good. The LED blinks when the transmitter or receiver 	TX_EN	23		TX_EN is an active high signal. RGMII Transmit Control: TX_CTRL combines transmit enable and transmit error signals. TX_EN is presented on the rising edge of TX_CLK and TX_ER on the falling edge of			
TX_D1       23       CLKOUT50M output of the device         TX_D2       26       In RMII Slave mode, TX_D[0,1] are synchronous to rising edge of Ref clock         TX_D3       27         LED_2/ TX_ER       28       Strap         This pin acts as LED_2 by default. It can be configured as GPIO or TX_ER as well. The LE is ON when link is negotiated for 10M (short reach). LED remains OFF otherwise.         LED_0       29       Strap         LED_i Activity Indication LED indicates transmit and receive activity in addition to the status the link. The LED is ON when link is good. The LED blinks when the transmitter or receiver active. This pin can also act as GPIO using register configuration.         CLKOUT/ LED_1       30       This pin provides Reference CLKOUT of 25 MHz as default to clock other module on the board. The pin can be configured to act as LED_1 using strap or register configuration. The LED is ON when link is negotiated for 10M (long reach). The LED remains OFF otherwise. When configured for CLK_OUT, reference clock is not affected by reset.         RST_N       31       RST_N: This pin is an active low reset input. Asserting this pin low for at least 25µs will forc a reset process to occur. Initiation of reset causes strap pins to be re-scanned and resets a	TX_D0	24		Transmit Data: In MII mode, the transmit data nibble received from the MAC is synchronous			
TX_D2       26       In RMII Slave mode, TX_D[0,1] are synchronous to rising edge of Ref clock         TX_D3       27       In RMII Slave mode, TX_D[0,1] are synchronous to rising edge of Ref clock         LED_2/ TX_ER       28       Strap       This pin acts as LED_2 by default. It can be configured as GPIO or TX_ER as well. The LE is ON when link is negotiated for 10M (short reach). LED remains OFF otherwise.         LED_0       29       Strap       LED : Activity Indication LED indicates transmit and receive activity in addition to the status the link. The LED is ON when link is good. The LED blinks when the transmitter or receiver active. This pin can also act as GPIO using register configuration.         CLKOUT/ LED_1       30       This pin provides Reference CLKOUT of 25 MHz as default to clock other module on the board. The pin can be configured to act as LED_1 using strap or register configuration. The LED is ON when link is negotiated for 10M (long reach). The LED remains OFF otherwise. When configured for CLK_OUT, reference clock is not affected by reset.         RST_N       31       RST_N: This pin is an active low reset input. Asserting this pin low for at least 25µs will force a reset process to occur. Initiation of reset causes strap pins to be re-scanned and resets and	TX_D1	25					
LED_2/ TX_ER28StrapThis pin acts as LED_2 by default. It can be configured as GPIO or TX_ER as well. The LE is ON when link is negotiated for 10M (short reach). LED remains OFF otherwise.LED_029StrapLED : Activity Indication LED indicates transmit and receive activity in addition to the status the link. The LED is ON when link is good. The LED blinks when the transmitter or receiver active. This pin can also act as GPIO using register configuration.CLKOUT/ LED_130This pin provides Reference CLKOUT of 25 MHz as default to clock other module on the board. The pin can be configured to act as LED_1 using strap or register configuration. The LED is ON when link is negotiated for 10M (long reach). The LED remains OFF otherwise.RST_N31RST_N: This pin is an active low reset input. Asserting this pin low for at least 25µs will force a reset process to occur. Initiation of reset causes strap pins to be re-scanned and resets and	TX_D2	26					
TX_ER       28       Strap       is ON when link is negotiated for 10M (short reach). LED remains OFF otherwise.         LED_0       29       Strap       LED : Activity Indication LED indicates transmit and receive activity in addition to the status the link. The LED is ON when link is good. The LED blinks when the transmitter or receiver active. This pin can also act as GPIO using register configuration.         CLKOUT/       30       This pin provides Reference CLKOUT of 25 MHz as default to clock other module on the board. The pin can be configured to act as LED_1 using strap or register configuration. The LED is ON when link is negotiated for 10M (long reach). The LED remains OFF otherwise. When configured for CLK_OUT, reference clock is not affected by reset.         RST_N       31       RST_N: This pin is an active low reset input. Asserting this pin low for at least 25µs will force a reset process to occur. Initiation of reset causes strap pins to be re-scanned and resets and resets and the state of the st		27					
LED_0       29       Strap       the link. The LED is ON when link is good. The LED blinks when the transmitter or receiver active. This pin can also act as GPIO using register configuration.         CLKOUT/       30       This pin provides Reference CLKOUT of 25 MHz as default to clock other module on the board. The pin can be configured to act as LED_1 using strap or register configuration. The LED is ON when link is negotiated for 10M (long reach). The LED remains OFF otherwise. When configured for CLK_OUT, reference clock is not affected by reset.         RST_N       31       RST_N: This pin is an active low reset input. Asserting this pin low for at least 25µs will force a reset process to occur. Initiation of reset causes strap pins to be re-scanned and resets and the strap of the strap pine to be reset.		28	Strap	This pin acts as LED_2 by default. It can be configured as GPIO or TX_ER as well. The LED is ON when link is negotiated for 10M (short reach). LED remains OFF otherwise.			
CLKOUT/ LED_1       30       board. The pin can be configured to act as LED_1 using strap or register configuration. The LED is ON when link is negotiated for 10M (long reach). The LED remains OFF otherwise. When configured for CLK_OUT, reference clock is not affected by reset.         RST_N       31       RST_N: This pin is an active low reset input. Asserting this pin low for at least 25µs will for a reset process to occur. Initiation of reset causes strap pins to be re-scanned and resets and	LED_0	29	Strap	LED : Activity Indication LED indicates transmit and receive activity in addition to the status of the link. The LED is ON when link is good. The LED blinks when the transmitter or receiver is active. This pin can also act as GPIO using register configuration.			
RST_N 31 a reset process to occur. Initiation of reset causes strap pins to be re-scanned and resets a		30		board. The pin can be configured to act as LED_1 using strap or register configuration. The LED is ON when link is negotiated for 10M (long reach). The LED remains OFF otherwise.			
	RST_N	31		RST_N: This pin is an active low reset input. Asserting this pin low for at least 25µs will force a reset process to occur. Initiation of reset causes strap pins to be re-scanned and resets all the internal registers of the PHY to default value.			
GPIO1         32         Strap         General Purpose Input or Output.	GPIO1	32	Strap	General Purpose Input or Output.			

#### Table 5-1. Internal PU/PD in various states

Pin #	Pin Name	Reset State	Active State (MII Mode)	Active State ( RMII Master Mode)	Active State ( RMII Slave Mode)	Active State (RGMII Mode)
1	DVDD	А	A	A	А	A
2	CEXT	А	A	А	А	A
3	VDDA	А	A	А	А	A
4	TX+	А	A	А	А	A
5	RX+	А	A	A	А	A
6	RX-	А	A	A	А	A



Table 5-1. Internal PU/PD in various states (continued)						
Pin #	Pin Name	Reset State	Active State ( MII Mode)	Active State ( RMII Master Mode)	Active State ( RMII Slave Mode)	Active State (RGMII Mode)
7	TX-	А	А	А	А	A
8	GPIO2	I,PD	I,PD	I,PD	I,PD	I,PD
9	XO	А	А	A	A	A
10	XI/50MHzIn	А	А	А	А	A
11	MDIO	ю	IO	IO	IO	10
12	MDC	I	I	I	I	1
13	RX_D3	I,PD	O,Hi-Z	I,PD	I,PD	O,Hi-Z
14	RX_D2	I,PD	O,Hi-Z	I,PD	I,PD	O,Hi-Z
15	RX_D1	I,PD	O,Hi-Z	O,Hi-Z	O,Hi-Z	O,Hi-Z
16	RX_D0	I,PD	O,Hi-Z	O,Hi-Z	O,Hi-Z	O,Hi-Z
17	VDDIO	Α	А	А	А	A
18	RX_DV/ CRS_DV	I,PD	O,Hi-Z	O,Hi-Z	O,Hi-Z	O,Hi-Z
19	RX_CLK/ 50MHz)RMI I_M	I,PD	O,Hi-Z	O,Hi-Z	O,Hi-Z	O,Hi-Z
20	RX_ER	I,PD	O,Hi-Z	O,Hi-Z	O,Hi-Z	I,PD
21	PWDN/INT	I,PU-9.5K Ω/OPEN DRAIN	I,PU-9.5KΩ/ OPEN DRAIN	I,PU-9.5KΩ/OPEN DRAIN	I,PU-9.5KΩ/OPEN DRAIN	I,PU-9.5KΩ/OPEN DRAIN
22	TX_CLK	I,PD	O,Hi-Z	I,PD	I,PD	I,PD
23	TX_EN	I,PD	I,PD	I,PD	I,PD	I,PD
24	TX_D0	I,PD	I,PD	I,PD	I,PD	I,PD
25	TX_D1	I,PD	I,PD	I,PD	I,PD	I,PD
26	TX_D2	I,PD	I,PD	I,PD	I,PD	I,PD
27	TX_D3	I,PD	I,PD	I,PD	I,PD	I,PD
28	LED_2/ TX_ER	I,PD	O,Hi-Z	O,Hi-Z	O,Hi-Z	O,Hi-Z
29	LED_0	I,PD	O,Hi-Z	O,Hi-Z	O,Hi-Z	O,Hi-Z
30	CLKOUT/ LED_1	I,PD(Only at POR)	O,Hi-Z	O,Hi-Z	O,Hi-Z	O,Hi-Z
31	RST_N	I,PU	I,PU	I,PU	I,PU	I,PU
32	GPIO1	I,PD	O,Hi-Z	O,Hi-Z	O,Hi-Z	O,Hi-Z

#### . . . \_ 4 1.4 ... . . , .... **،**۲

The definitions below define the functionality of the I/O cells for each pin. (a) Type: I - Input (b) Type: O - Output (c) Type: I/O - Input/Output (d) Type OD - Open Drain (e) Type: PD, PU - Internal Pulldown/Pullup (g) Type HI-Z : floating (h) Type:A - Analog



# 6 Specifications

#### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

PARA	METER	MIN	MAX	UNIT
	DVDD 1.0	-0.3	1.4	V
	VDDA 1.8	-0.3	4	V
Supply voltage	VDDA 3.3	-0.3	4	V
Supply voltage	VDDIO (3.3)	-0.3	4	V
	VDDIO (2.5)	-0.3	3	V
	VDDIO (1.8)	-0.3	2.1	V
Pins	MDI (Tx+, Tx-, Rx+, Rx-)	-0.3	4	V
Pins	TX_D[0:3],RX_D[0:3], TX_CLK, RX_CLK, TX_EN, RX_DV, RX_ER, MDIO, MDC, LED0, LED1, LED2	-0.3	VDDIO + 0.3	V
Pins	INT/PWDN, RESET	-0.3	VDDIO + 0.3	V
Pins	XI Oscillator Input	-0.3	VDDIO+0.3	V

(1) Stresses beyond those listed under Absolute Maximum Rating may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Condition. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 6.2 ESD Ratings

	Parameter				
V <sub>(ESD)</sub>	V(ESD) Electrostatic discharge	Human-body model (HBM), perANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	All pins except MDI	+/-2000	V
V <sub>(ESD)</sub>	V(ESD) Electrostatic discharge	Human-body model (HBM), perANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	MDI pins	+/-6000	V
V <sub>(ESD)</sub>	V(ESD) Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22- C101 <sup>(2)</sup>	All Pins	+/-1000	V

(1) JEDEC document JEP155 states that 500 V HBM allows safe manufacturing with a standard ESD control process. Manufacturing withless than 500 V HBM is possible with the necessary precautions.

(2) JEDEC document JEP157 states that 250 V CDM allows safe manufacturing with a standard ESD control process. Manufacturing withless than 250 V CDM is possible with the necessary precautions. Pins listed as ±500 V may actually have higher performance.

#### **6.3 Recommended Operating Conditions**

over operating free-air temperature range (unless otherwise noted)

	Parameter	MIN	NOM	MAX	UNIT
DVDD 1.0	Digital Supply	0.90	1.0	1.1	V
VDDA 1.8	Analog Supply	1.62	1.8	1.98	V
VDDA 3.3	Analog Supply	3.0	3.3	3.6	V
	Digital Supply Voltage, 1.8V operation	1.62	1.8	1.98	
VDDIO	Digital Supply Voltage, 2.5V operation	2.25	2.5	2.75	V
	Digital Supply Voltage, 3.3V operation	3.0	3.3	3.6	
T <sub>A</sub>	Operating Ambient Temperature	-40		105	°C



#### 6.4 Thermal Information

	THERMAL METRIC <sup>(1)</sup>	32PIN QFN	UNIT
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	52	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	42	°C/W
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	10	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	30	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	2	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	30	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

# **6.5 Electrical Characteristics**

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

	PARAMETER	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT
IEEE Tx CONFORMANCE (10BaseT1L External Terminations)						
1V p2p	Vod : Output Differential Voltage		0.85	1.0	1.05	V
2.4V p2p	Vod : Output Differential Voltage		2.04	2.4	2.56	V



# over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER	CONSUMPTION (Dual Analog Supply,	1V p2p mode)			<b>I</b>	
	DVDD1.0	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range		3.5	7.5	mA
	AVDD1.8	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range		16	21.5	mA
	DVDD1.0	Reset			6	mA
	AVDD1.8	Reset			5	mA
	DVDD1.0	IEEE Power Down			5	mA
	AVDD1.8	IEEE Power Down			5	mA
POWER	CONSUMPTION (Dual Analog Supply,	2.4V p2p mode)				
	DVDD1.0	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range		3.5	7	mA
	AVDD3.3	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range		22	32	mA
	AVDD3.3	Reset			5	mA
POWER	CONSUMPTION Single Analog Supply	, 1v p2p, 200 meters)				
Temp: -40 to 105C	AVDD3.3	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range		19	26	mA
Temp: -40 to 105C	AVDD1.8	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range		19	26.5	mA
POWER	CONSUMPTION Single Analog Supply	, 2.4 Vp2p, 1000 meters)			ı	
Temp: -40 to 105C	AVDD3.3	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range		26	38	mA
Power (	Consumption VDDIO (MII Interface)					
	VDDIO1.8	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range		2.75	4	mA
	VDDIO2.5	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range		4	5	mA



PARAMETER	ture range (unless otherwise noted) <sup>(1)</sup> TEST CONDITIONS	MIN TYP	MAX	UNIT
VDDIO3.3	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range	5	7	mA
Power Consumption VDDIO (RM	III Master Interface)			
VDDIO1.8	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range	9.5	12	mA
VDDIO2.5	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range	12.5	17	mA
VDDIO3.3	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range	16.5	22	mA
Power Consumption VDDIO (RM	III Slave Interface)			
VDDIO1.8	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range	3	4	mA
VDDIO2.5	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range	4	5	mA
VDDIO3.3	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range	5.5	7	mA
Power Consumption VDDIO ( RI	/III Master 5 MHz)			
VDDIO1.8	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range	3.5	4.5	mA
VDDIO2.5	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range	4.5	5	mA
VDDIO3.3	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range	6	8	mA
Power Consumption VDDIO (RC	iMII Interface)			
VDDIO1.8	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range	3	4	mA

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
	VDDIO2.5	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range		4	5.5	mA
	VDDIO3.3	Typ : 100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Temp: 25C Max :100% Traffic, Random Size : 64 to 1512 Bytes, Random Content, Across Process, Voltage and Temperature range		5.5	7.5	mA
POWER	CONSUMPTION Low power modes					
Temp: -40 to 105C	VDDIO1.8	Reset			3	mA
	VDDIO2.5	Reset			5	mA
	VDDIO3.3	Reset			7	mA
Temp: -40 to 105C	VDDIO1.8	IEEE PowerDown			3	mA
	VDDIO2.5	IEEE PowerDown			4	mA
	VDDIO3.3	IEEE PowerDown			5	mA
BOOTS	TRAP DC CHARACTERISTICS (2 Level)					
V <sub>IH_3v3</sub>	High Level Bootstrap Threshold : 3V3		1.3			V
V <sub>IL_3v3</sub>	Low Level Bootstrap Threshold : 3V3				0.6	V
V <sub>IH_2v5</sub>	High Level Bootstrap Threshold: 2V5		1.3			V
V <sub>IL_2v5</sub>	Low Level Bootstrap Threshold : 2V5				0.6	V
V <sub>IH_1v8</sub>	High Level Bootstrap Threshold:1V8		1.3			V
V <sub>IL_1v8</sub>	Low Level Bootstrap Threshold :1V8				0.6	V



# over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
IO CHA	RACTERISTICS					
V <sub>IH</sub>	High Level Input Voltage	VDDIO = 3.3V ±10%	2			V
V <sub>IL</sub>	Low Level Input Voltage	VDDIO = 3.3V ±10%			0.8	V
V <sub>OH</sub>	High Level Output Voltage	I <sub>OH</sub> = -2mA, VDDIO = 3.3V ±10%	2.4			V
V <sub>OL</sub>	Low Level Output Voltage	I <sub>OL</sub> = 2mA, VDDIO = 3.3V ±10%			0.4	V
V <sub>IH</sub>	High Level Input Voltage	VDDIO = 2.5V ±10%	1.7			V
V <sub>IL</sub>	Low Level Input Voltage	VDDIO = 2.5V ±10%			0.7	V
V <sub>OH</sub>	High Level Output Voltage	I <sub>OH</sub> = -2mA, VDDIO = 2.5V ±10%	2			V
V <sub>OL</sub>	Low Level Output Voltage	I <sub>OL</sub> = 2mA, VDDIO = 2.5V ±10%			0.4	V
V <sub>IH</sub>	High Level Input Voltage	VDDIO = 1.8V ±10%	0.65*VD DIO			V
V <sub>IL</sub>	Low Level Input Voltage	VDDIO = 1.8V ±10%			0.35*VD DIO	V
V <sub>OH</sub>	High Level Output Voltage	I <sub>OH</sub> = -2mA, VDDIO = 1.8V ±10%	VDDIO-0 .45			V
V <sub>OL</sub>	Low Level Output Voltage	I <sub>OL</sub> = 2mA, VDDIO = 1.8V ±10%			0.45	V
I <sub>IH</sub>	Input High Current	$T_A = -40^{\circ}C$ to 105°C, VIN=VDDIO	-15		15	μA
I <sub>IL</sub>	Input Low Current	$T_A = -40^{\circ}C$ to 105°C, VIN=GND	-10		10	μA
R <sub>pulldn</sub>	Internal Pull Down Resistor			9	11.5	kΩ
R <sub>pullup</sub>	Internal Pull Up Resistor			9	11.5	kΩ
XI V <sub>IH</sub>	High Level Input Voltage		1.2			V
XI V <sub>IL</sub>	Low Level Input Voltage				0.6	V
C <sub>IN</sub>	Input Capacitance XI			1		pF
C <sub>IN</sub>	Input Capacitance INPUT PINS (TX_D[3:0], TX_EN, TX_CLK, MDC)			5		pF
C <sub>OUT</sub>	Output Capacitance XO			1		pF
C <sub>OUT</sub>	Output Capacitance OUTPUT PINS			5		pF
R <sub>series</sub>	Integrated MAC Series Termination Resistor	RX_D[3:0], RX_ER, RX_DV, RX_CLK		50		Ω
	LED drive strength			8		mA
	GPIO Driver Strength			8		mA

(1) Ensured by production test, characterization or design



# 6.6 Timing Requirements (1)

	PARAMETER	TEST CONDITIONS	MIN	NOM	МАХ	UNIT
POWER	-UP TIMING (Single and Dual supply mode)					
T1	Supply ramp delay offset: For all supplies (DVDD, VDDA, VDDIO)	First Supply ramp to last supply ramp			200	ms
T2	Last Supply powerup to RESET Complete and SMI ready: Post power-up stabilization time prior to MDC preamble for register access				60	ms
T4	Supply ramp rate: For all supplies (DVDD, VDDA, VDDIO)	(20% to 80%)	0.2		40	ms
	Powerup to Strap latchin: Hardware configuration pins transition to output drivers				60	ms
	Pedestal Voltage on DVDD, VDDA, VDDIO before Power Ramp				0.3	V
RESET	TIMING					
T1	RESET PULSE Width: Miminum Reset pulse width to be able to reset		10			us
T2	Reset to SMI ready: Post reset stabilization time prior to MDC preamble for register access				30	us
	Reset to Strap latchin: Hardware configuration pins transition to output drivers				1050	ns
	Reset to 10Base-T1L Auto Neg Signalling				9000	us
	Reset to RMII Master clock				35	us
MII 10M	Timings					
T1	TX_CLK High / Low Time		190	200	210	ns
T2	TX_D[3:0], TX_ER, TX_EN Setup to TX_CLK		25			ns
Т3	TX_D[3:0], TX_ER, TX_EN Hold from TX_CLK		0			ns
T1	RX_CLK High / Low Time		160	200	240	ns
T2	RX_D[3:0], RX_ER, RX_DV Delay from RX_CLK rising		100		300	ns
RGMII O	DUTPUT TIMING (10M)					
T <sub>skewT</sub>	Data to Clock Output Skew (Non-Delay Mode)	5 pF Load	-2		2	ns
T <sub>skewT</sub> (delay)	Data to Clock Output Skew (Integrated Delay Mode)	5 pF Load	40			ns
T <sub>cyc</sub>	Clock Cycle Duration		-360	400	440	ns
	Duty Cycle		45	50	55	%
	Rise / Fall Time ( 20% to 80%)				3	ns
RGMII IN	NPUT TIMING (10M)				·	
T <sub>skewR</sub>	TX data to clock input skew (Integrated Delay Mode)		-4		4	ns
T <sub>setupR</sub>	TX data to clock input setup (Non-Delay Mode)		40			ns
T <sub>holdR</sub>	TX clock to data input hold (Non-Delay Mode)		40			ns
RMII MA	STER TIMING					
T1	RMII Master Clock Period			20		ns
	RMII Master Clock Duty Cycle		35		65	%
T2	TX_D[1:0], TX_ER, TX_EN Setup to RMII Master Clock	25 pF Load	4			ns
Т3	TX_D[1:0], TX_ER, TX_EN Hold from RMII Master Clock	25 pF Load	2			ns
T4	RX_D[1:0], RX_ER, CRS_DV Delay from RMII Master Clock rising edge	25 pF Load	4	10	14	ns
RMII SL	AVE TIMING					
T1	Input Reference Clock Period			20		ns
	Reference Clock Duty Cycle		35		65	%



#### (1)

	PARAMETER	TEST CONDITIONS	MIN	NOM	MAX	UNIT
T2	TX_D[1:0], TX_ER, TX_EN Setup to XI Clock rising		4			ns
Т3	TX_D[1:0], TX_ER, TX_EN Hold from XI Clock rising		2			ns
T4	RX_D[1:0], RX_ER, CRS_DV Delay from XI Clock rising		4		14	ns
RMII N	laster Timing ( 5 MHz)					
	Frequency			5		MHz
	Duty Cycle		40		60	%
T2	TX_D[3:0], TX_ER, TX_EN setup to Master Clock		10			ns
Т3	TX_D[3:0], TX_ER, TX_EN hold from Master Clock		10			ns
T4	RX_D[3:0], RX_ER, RX_DV Delay from 5 MHz Clock		50	100	150	ns
SMI TI	MING	-				
T1	MDC to MDIO (Output) Delay Time		0		10	ns
T2	MDIO (Input) to MDC Setup Time		10			ns
Т3	MDIO (Input) to MDC Hold Time		10			ns
T4	MDC Frequency			1	1.75	MHz

SNLS656C - AUGUST 2020 - REVISED DECEMBER 2020



(1)

	PARAMETER	TEST CONDITIONS	MIN	NOM	МАХ	UNIT
OUTPUT	CLOCK TIMING (25MHz clockout)					
	Frequency (PPM)		-100		100	-
	Duty Cycle		40		60	%
	Rise Time				5000	ps
	Fall Time				5000	ps
	Jitter (RMS - long term)				40	ps
	Frequency			25		MHz
	RefCLK to clock out delay				3000	ps
Output C	lock 50 MHz timing				1	
	Frequency (PPM)		-50		50	ppm
	Duty Cycle		35		65	%
	Rise time				5000	ps
	Fall Time				5000	ps
	Jitter (Long Term 10,000 Cyles)				650	ps
25MHz IN	PUT CLOCK tolerance					
	Frequency Tolerance		-100		+100	ppm
	Jitter Tolerance (RMS)				40	ps
	Rise / Fall Time (10%-90%)				8	ns
	Jitter Tolerance (Accumulated)				500	ps
	Duty Cycle		40		60	%
50MHz In	put Clock Tolerance					
	Frequency Tolerance		-100		+100	ppm
	Jitter Tolerance (RMS)				40	ps
	Rise / Fall Time (10%-90%)			· · · · · ·	4	ns
	Jitter Tolerance (Accumulated)				250	ps
	Duty Cycle		40		60	%
TRANSM	IT LATENCY TIMING					
Copper	RGMII to Cu (10M) : Rising edge TX_CLK with assertion TX_CTRL to SSD symbol on MDI				3000	ns
Copper	MII to Cu (10M): Rising edge TX_CLK with assertion TX_EN to SSD symbol on MDI				750	ns
Tx_RMII	Slave RMII Rising edge XI clock with assertion TX_EN to SSD symbol on MDI (10M)				2800	ns
Tx_RMII	Master RMII Rising edge clock with assertion TX_EN to SSD symbol on MDI (10M)				2800	ns
RECEIVE	LATENCY TIMING					
Copper	Cu to RGMII (10M): SSD symbol on MDI to Rising edge of RX_CLK with assertion of RX_CTRL				5000	ns
Copper	Cu to MII (10M): SSD symbol on MDI to Rising edge of RX_CLK with assertion of RX_DV				5100	ns
Rx_RMII	SSD symbol on MDI to Slave RMII Rising edge of XI clock with assertion of CRS_DV (10M)				5700	ns
Rx_RMII	SSD symbol on MDI to Master RMII Rising edge of Master clock with assertion of CRS_DV (10M)				5800	ns

(1) Ensured by production test, characterization or design



# 6.7 Timing Diagrams

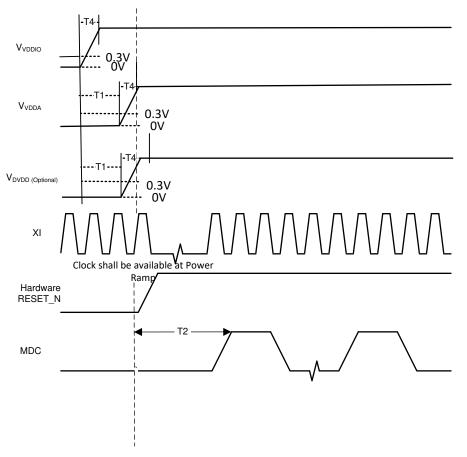


Figure 6-1. Power-Up Timing



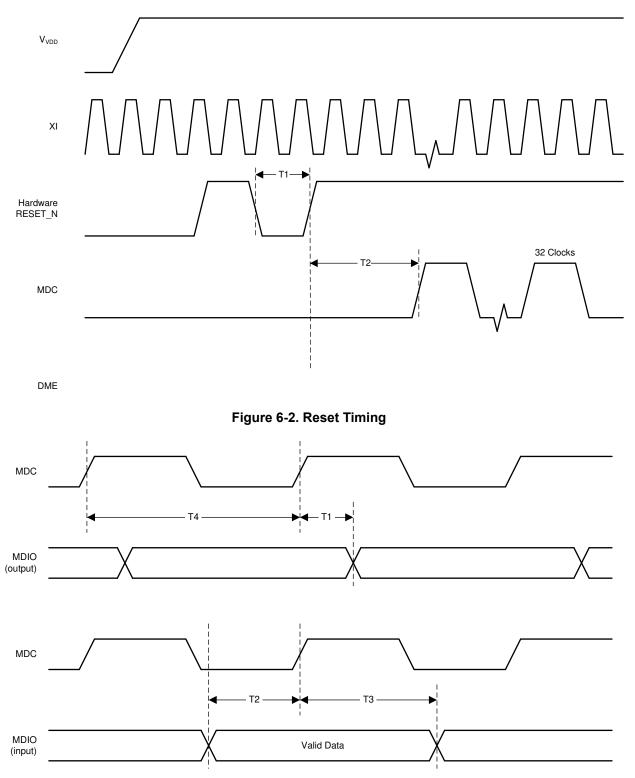
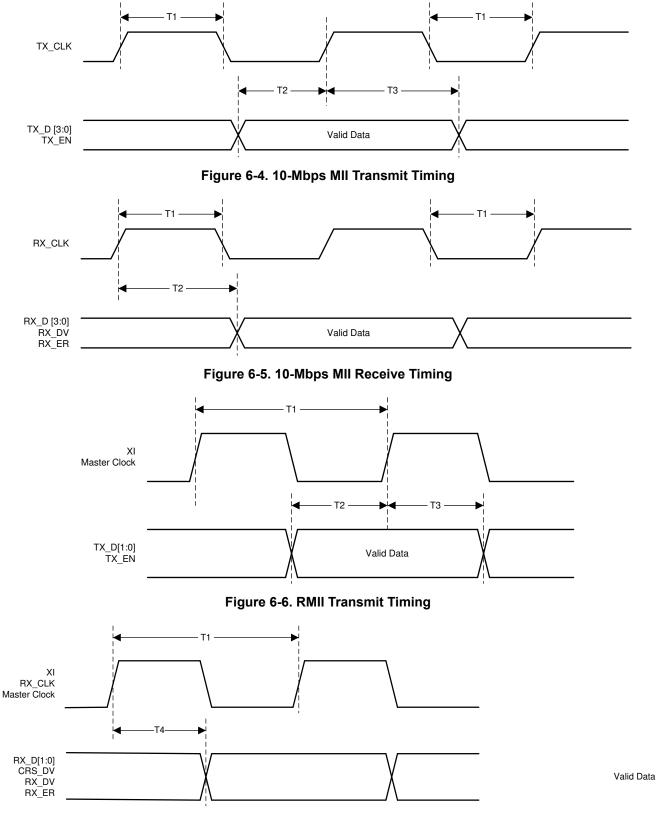


Figure 6-3. Serial Management Timing









# 7 Detailed Description

### 7.1 Overview

The DP83TD510E is a physical-layer transceiver compliant to IEEE 802.3cg 10BaseT1L standards. The PHY use low noise coupled signal processing reciever architecture to offer longer cable reach along with ultra-low power consumption. The device supports both 2.4-V p2p and 1-V p2p voltage mode as defined by IEEE 802.3cg 10Base-T1L specifications. It supports multiple MAC interface (MII, Reduced Media Independent Interface (RMII), RGMII and low power Reduced MII) for direct connection to Media Access Controller (MAC). The device also supports back-to-back RMII mode and RGMII in unmanaged mode to provide range extension and repeater functionality.

The device is designed to operate from a single 3.3-V power supply and has integrated LDO to provide the voltage rails required for internal blocks. The device has an option to feed digital power externally to achieve lowest power consumption. The device allows I/O voltage interfaces for 3.3 V, 2.5 V or 1.8 V. Automatic supply configuration within the DP83TD510E allows for any combination of VDDIO supply without the need for additional configuration settings.

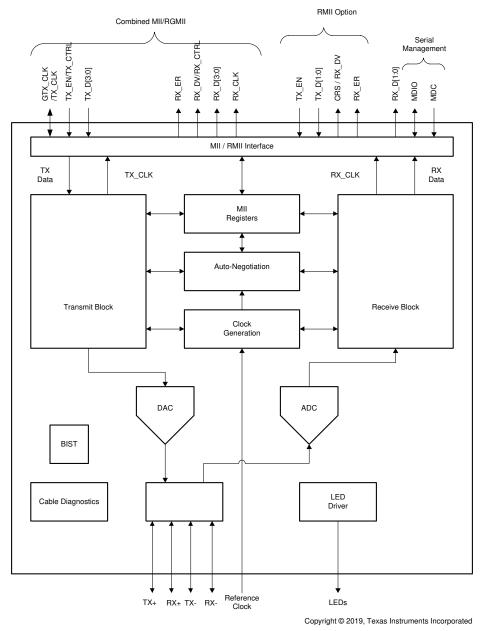
The DP83TD510E is designed for use in intrinsically safe Ethernet advanced physical layer (APL) systems. Ethernet-APL is an Ethernet specification based on the IEEE 802.3.cg 10BASE-T1L standard and was developed to streamline implementation of Ethernet networking in process automation systems with intrinsic safety requirements.

A key design consideration of intrinsically safe Ethernet-APL systems – especially systems designed for use in hazardous environments with explosive potential – is the ability to reduce Ethernet PHY power levels and temperature during system failure conditions. By supporting external termination resistors, the DP83TD510E can reduce inrush current and maintain lower operating temperatures when used in long-distance process automation applications, such as field transmitters. DP83TD510E offers support for both external termination Configuration as defined in Annex A of the IEEE 802.3cg specifications. PHY is designed with innovative hybrid reciever to adjust itself for external termination implementation. For non intrinsic safe applciations, DP83TD510E offers simplied external termination configuration with minimal external passives.

The DP83TD510E Diagonstic Tool includes TDR (Time Domain Reflectometry), ALCD (Active Link Cable Diagnostics), SQI (Signal Quality Indicator), mulitple Loopbacks and Integrated PRBS Packet Generator to ease debugging during development and detecting faulty conditions in field.



### 7.2 Functional Block Diagram



### 7.3 Feature Description

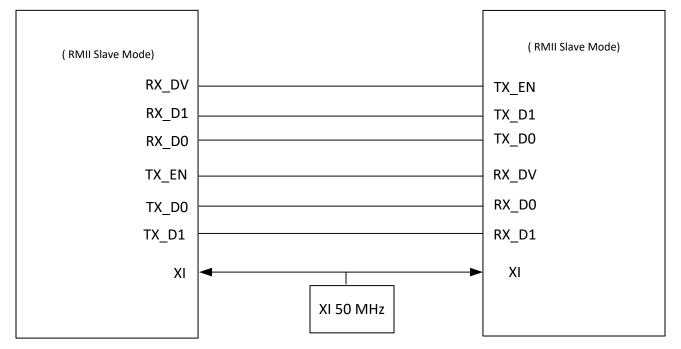
#### 7.3.1 Auto-Negotiation (Speed Selection)

Auto-Negotiation provides a mechanism for exchanging configuration information between the two ends of a link segment. The DP83TD510E supports auto-negotiation for Low Speed Modes (LSM) as defined in IEEE 802.3cg specification for 10BaseT1L. Auto-negotiation ensures that the highest common speed is selected based on the advertised abilities of the link partner and the local device. DP83TD510E (default) broadcast both 2.4V p2p and 1.V p2p capabilities. It offers HW strap or register based configuration to broadcast only 1V p2p capability. Refer to straps section for details.

#### 7.3.2 Repeater Mode

The DP83TD510E provides an option to enable repeater mode functionality to extend the cable reach. Two DP83TD510E can be connected in back to back mode without any external configuration. A hardware strap is provided to configure the CRS\_DV pin of RMII interface to RX\_DV pin for back to back operation. Refer to RMII

Repeater Mode for the RMII pin connection to enable repeater mode on the DP83TD510E. DP83TD510E RGMII MAC mode can also be used for Repeater Mode. With RGMII Mac, mac interface clock runs at 2.5 MHz and will dissipiate less power and offer improved signal integrity.





### 7.3.3 Media Convertor

The DP83TD510E provides option to enable media conversion (Single Pair Ethernet to Standard 10Base-Te CAT5e) functionality using strap configurations (no external MCU programming is needed). The DP83TD510E can be connected to 10 Base-Te PHY (For example : DP83822, DP83826I) to covert the medium from Single Pair Ethernet to Standard Ethernet(CAT5e). This can be done using RMII or RGMII mac interface can be used to perform the media conversion. Refer to below figures for connections. With RGMII Mac, mac interface clock runs at 2.5MHz and will dissipiate less power and offer improved signal integrity.



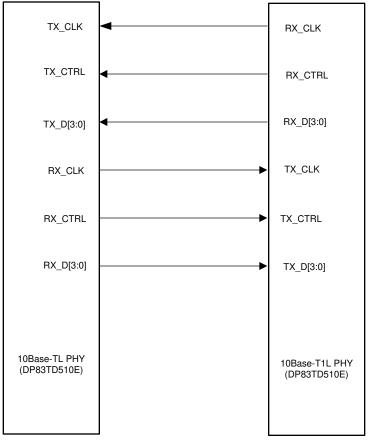
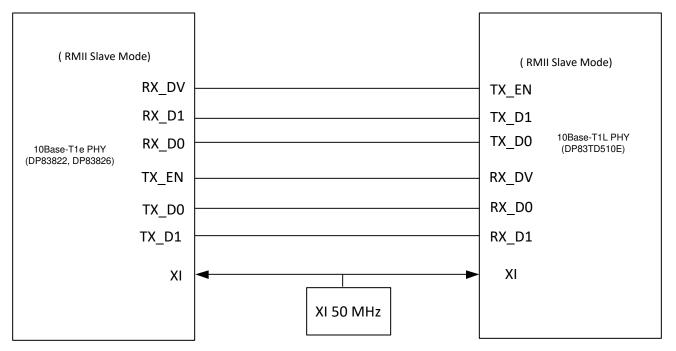


Figure 7-2. Mediaconvertor using RGMII MAC interface







#### 7.3.4 Clock Output

The DP83TD510E has several clock output configuration options. An external crystal or CMOS-level oscillator provides the stimulus for the internal PHY reference clock. The local reference clock acts as the central source for all clocking within the device.

All clock configuration options are enabled using the IO MUX GPIO Control Register

Clock options supported by the DP83TD510E include:

- MAC IF clock
- XI clock
- Free-running clock
- Recovered clock

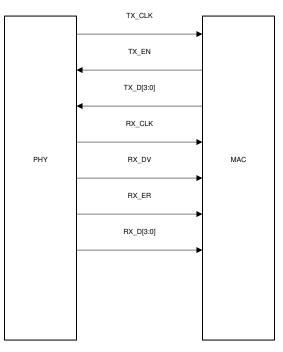
#### 7.3.5 Media Independent Interface (MII)

The Media Independent Interface is a synchronous 4-bit wide nibble data interface that connects the PHY to the MAC. The MII is fully compliant with IEEE 802.3-2002 clause 22.

The MII signals are summarized in Table 7-1.

#### Table 7-1. MII Signals

FUNCTION	PINS
Data Signals	TX_D[3:0]
	RX_D[3:0]
Transmit and Receive Signals	TX_EN
	RX_DV



#### Figure 7-4. Mll Signaling

Additionally, the MII interface includes the carrier sense signal (CRS), as well as a collision detect signal (COL). The CRS signal asserts to indicate the reception or transmission of data. The COL signal asserts as an indication of a collision which can occur during half-duplex mode when both transmit and receive operations occur simultaneously.



#### 7.3.6 Reduced Media Independent Interface (RMII)

The DP83TD510E incorporates the Reduced Media Independent Interface (RMII) as specified in the RMII specification v1.2. The purpose of this interface is to provide a reduced pin count alternative to the IEEE 802.3 MII as specified in Clause 22. Architecturally, the RMII specification provides an additional reconciliation layer on either side of the MII, but can be implemented in the absence of an MII. The DP83TD510E offers two types of RMII operations: RMII Slave and RMII Master. In RMII Master operation, the DP83TD510E operates off of either a 25-MHz CMOS-level oscillator connected to XI pin or a 25-MHz crystal connected across XI and XO pins. A 50-MHz output clock referenced from DP83TD510E can be connected to the MAC. In RMII Slave operation, the DP83TD510E operates off of a 50-MHz CMOS-level oscillator connected to scillator connected to the MAC. In RMII Slave operation, the DP83TD510E operates off of a 50-MHz CMOS-level oscillator connected to scillator connected to the MAC. In RMII Slave operation, the DP83TD510E operates off of a 50-MHz CMOS-level oscillator connected to the MAC. In RMII Slave operation, the MAC. Alternatively, in RMII Slave mode, the PHY can run from a 50-MHz clock provided by the Host MAC.

The RMII specification has the following characteristics:

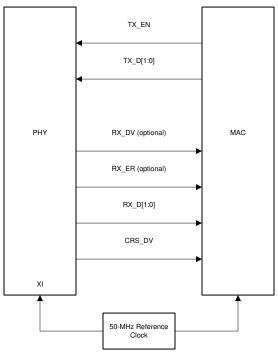
- · Single clock reference sourced from the PHY to MAC or from an external source fed both to MAC and PHY
- Independent 2-bit wide transmit and receive data paths
- Usage of CMOS signal levels, the same levels as the MII interface

In this mode, data transfers are two bits for every clock cycle using the internal 50-MHz reference clock for both transmit and receive paths.

The RMII signals are summarized in Table 7-2.

#### Table 7-2. RMII Signals

FUNCTION	PINS
Receive Data Lines	TX_D[1:0]
Transmit Data Lines	RX_D[1:0]
Receive Control Signal	TX_EN
Transmit Control Signal	CRS_DV







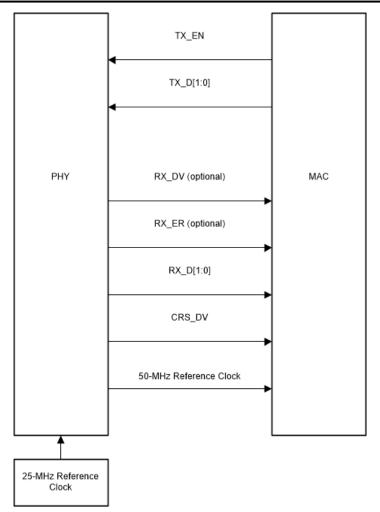


Figure 7-6. RMII Master Signaling

Data on TX\_D[1:0] are latched at the PHY with reference to the clock edges on the XI pin. Data on RX\_D[1:0] are latched at the MAC with reference to the same clock edges on the XI pin in RMII Slave Mode. For RMII Master mode, data is latched wrt the CLKOUT50M output from the PHY.

In addition, CRX\_DV can be configured as RX\_DV signal. It allows a simpler method of recovering receive data without the need to separate RX\_DV from the CRS\_DV indication.

#### 7.3.7 RMII Low Power 5-MHz Mode

DP83TD510E supports a new MAC Mode called RMII Master Low Power Mode. The interface is similar to the RMII master mode but runs at 5 MHz resulting in power dissipation savings. DP83TD510E offers 5-MHz clock output and data is sampled to this clock. An application can use the same pin map as RMII for this mode.

#### 7.3.8 RGMII Interface

DP83TD510E offers RGMII MAC interface as defined by Reduced Gigabit Media Independent Interface (RGMII) as specified by RGMII version 2.0. RGMII is designed to reduce the number of pins required to connect the MAC and PHY. To accomplish this goal, the control signals are multiplexed. Both rising and falling edges of the clock are used to sample the control signal pin on the transmit and receive paths. For 10-Mbps operation, RX\_CLK and TX\_CLK operate at 2.5 MHz. The timing specifications are relaxed compared to RGMII 1000M interface specifications. Refer to timing sections on timing specifications for this mode.

Table 7-	3. RGMII Signals	
Function	PINs	
		_



Table 7-3. RGMII Signals (continued)					
Data Signals	TX_D[3:0]				
	RX_D[3:0]				
Transmit and Recieve Clocks	TX_CLK				
	RX_CLK				
Transmit and Recieve Signals	TX_CTRL				
	RX_CTRL				

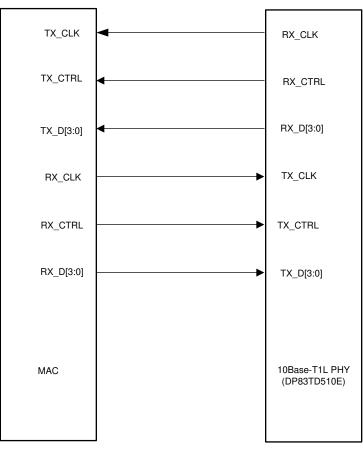


Figure 7-7. RGMII Signalling



#### 7.3.9 Serial Management Interface

The Serial Management Interface provides access to the DP83TD510E internal register space for status information and configuration. The SMI is compatible with IEEE 802.3 clause 22 and clause 45. The implemented register set consists of the registers required by IEEE 802.3 plus several others to provide additional visibility and controllability of the DP83TD510E.

The SMI includes the management clock (MDC) and the management input/output data pin (MDIO). MDC is sourced by the external management entity, also called Station (STA), and can run at a maximum clock rate of 1.75 MHz. MDC is not expected to be continuous and can be turned off by the external management entity when the bus is idle.

MDIO is sourced by the external management entity and by the PHY. The data on the MDIO pin is latched on the rising edge of the MDC. The MDIO pin requires a pullup resistor (2.2 k $\Omega$ ) which pulls MDIO high during IDLE and turnaround.

Up to 16 PHYs can share a common SMI bus. To distinguish between the PHYs, during power up or hardware reset, the DP83TD510E latches the Phy\_Address[3:0] configuration pins to determine its address.

The management entity must not start an SMI transaction in the first cycle after power up or hardware reset, it shall wait for powerup and reset to complete. Refer to timing section for power up and reset time. In normal MDIO transactions, the register address is taken directly from the management-frame reg\_addr field, thus allowing direct access to 32 16-bit registers (including those defined in IEEE 802.3 and vendor specific). The data field is used for both reading and writing. The Start code is indicated by a <01> pattern. This pattern ensures that the MDIO line transitions from the default idle line state. Turnaround is defined as an idle bit time inserted between the Register Address field and the Data field. To avoid contention during a read transaction, no device may actively drive the MDIO signal during the first bit of turnaround. The addressed DP83TD510E drives the MDIO with a zero for the second bit of turnaround and follows this with the required data.

For write transactions, the station-management entity writes data to the addressed DP83TD510E, thus eliminating the requirement for MDIO Turnaround. The turnaround time is filled by the management entity by inserting <10>.

Clock shall be provided during the <idle> period to complete the transaction.

SMI PROTOCOL	<idle><start><op code=""><phy address=""><reg addr=""><turnaround><data><idle></idle></data></turnaround></reg></phy></op></start></idle>
Read Operation	<idle>&lt;01&gt;&lt;10&gt;<aaaaa><rrrrr><z0><xxxx xxxx=""><idle></idle></xxxx></z0></rrrrr></aaaaa></idle>
Write Operation	<idle>&lt;01&gt;&lt;01&gt;<aaaaa><rrrr>&lt;10&gt;<xxxx xxxx=""><idle></idle></xxxx></rrrr></aaaaa></idle>

#### Table 7-4. SMI Protocol



#### 7.3.10 Loopback Modes

There are several loopback options within the DP83TD510E that test and verify various functional blocks within the PHY. Enabling loopback modes allow for in-circuit testing of the digital and analog data paths. The DP83TD510E may be configured to any one of the Near-End Loopback modes or to the Far-End (reverse) Loopback mode. MII Loopback is configured using the Control Register (BMCR, address 0x0000). All other loopback modes are enabled using the BIST Control Register (BISCR, address 0x0016).

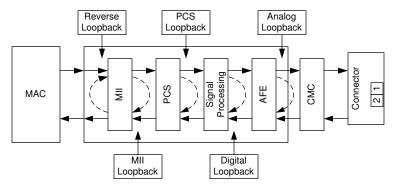


Figure 7-8. Loopback Test Modes

#### 7.3.10.1 MII Loopback

MII Loopback is the shallowest loop through the PHY. It is a useful test mode to validate communications between the MAC and the PHY. When in MII Loopback, data transmitted from a connected MAC on the TX path is internally looped back in the DP83TD510E to the RX pins where it can be checked by the MAC.

#### 7.3.10.2 PCS Loopback

PCS Loopback occurs in the PCS layer of the PHY. No signal processing is performed when using PCS Loopback.

#### 7.3.10.3 Digital Loopback

Digital Loopback includes the entire digital transmit and receive paths. Data is looped back prior to the analog circuitry.

Digital Loopback is enabled by setting bit[2] in the BISCR and register configuration 0x0883[0] = 0x1.

#### 7.3.10.4 Analog Loopback

Analog Signals can be looped back after the analog front-end.

#### 7.3.10.5 Far-End (Reverse) Loopback

Far-End (Reverse) loopback is a special test mode to allow PHY testing with a link partner. In this mode, data that is received from the link partner passes through the PHY's receiver, is looped back at the MAC interface and then transmitted back to the link partner. While in Reverse Loopback mode, all data signals that come from the MAC are ignored.

Please refer to DP83TD510 Cable diagnostics App note :SNLA364 for detailed procedure.

#### 7.3.11 BIST Configurations

The DP83TD510E incorporates an internal PRBS Built-in Self-Test (BIST) circuit to accommodate in-circuit testing and diagnostics. The BIST circuit can be used to test the integrity of transmit and receive data paths. The BIST can be performed using both internal loopbacks (digital or analog). The BIST simulates pseudo-random data transfer scenarios in format of real packets and Inter-Packet Gap (IPG) on the lines. The BIST allows full control of the packet lengths and the IPG.

Please refer to DP83TD510 Cable diagnostics App note :SNLA364 for detailed procedure.



#### 7.3.12 Cable Diagnostics

With the vast deployment of Ethernet devices, the need for a reliable, comprehensive and user-friendly cable diagnostic tool is more important than ever. The wide variety of cables, topologies and connectors deployed results in the need to non-intrusively identify and report cable faults. The DP83TD510E offers Time Domain Reflectometry (TDR), SQI (Signal Quality Indicator) and ALCD (Active Link Cable Diagnosticcs) capabilities in its cable diagnostic tool kit.

#### 7.3.12.1 TDR

The DP83TD510E uses Time Domain Reflectometry (TDR) to determine the quality of the cables, connectors and terminations in addition to estimating the cable length. Some of the possible problems that can be diagnosed include opens, shorts, cable impedance mismatch, bad connectors, termination mismatches, cross faults, cross shorts and any other discontinuities along the cable.

The DP83TD510E transmits a test pulse of known amplitude (1 V) down each of the two pairs of an attached cable. The transmitted signal continues down the cable and reflects from each cable imperfection, fault, connector and from the end of the cable itself. After the pulse transmission, the DP83TD510E measures the return time and amplitude of all these reflected pulses. This technique enables measuring the distance and magnitude (impedance) of non-terminated cables (open or short), discontinuities (bad connectors) and improperly terminated cables with ±1-m accuracy.

For all TDR measurements, the transformation between time of arrival and physical distance is done by the external host using minor computations (such as multiplication, addition and lookup tables). The host must know the expected propagation delay of the cable, which depends, among other things, on the cable category (for example, CAT5, CAT5e, or CAT6).

TDR measurement is allowed in the following scenarios:

- While the Link Partner is disconnected cable is unplugged at the other side
- Link Partner is connected but remains "quiet" (for example, in power down mode)
- TDR could be automatically activated when the link fails or is dropped

TDR Auto-Run can be enabled by using bit[8] in the Control Regsiter #1 (CR1, address 0x0009). When a link drops, TDR will automatically execute and store the results in the respective TDR Cable Diagnostic Location Result Registers #1 - #5 (CDLRR, addresses 0x0180 to 0x0184) and the Cable Diagnostic Amplitude Result Registers #1 - #5 (CDLAR, addresses 0x0185 to 0x0189). TDR can also be run manually using bit[15] in the Cable Diagnostic Control Register (CDCR, address 0x001E). Cable diagnostic status is obtained by reading bits[1:0] in the CDCR. Additional TDR functions including cycle averaging and crossover disable can be found in the Cable Diagnostic Specific Control Register (CDSCR, address 0x0170).

#### ALCD (Active Link Cable Diagnostics)

While TDR offers a way to measure cable length of a system prior to establishing a link, Active Link Cable

Diagnostic (ALCD) allows the PHY to determine the cable length during an active link with its link partner. It uses passive digital signal processing along with pre-defined cable parameters to achieve the highest accuracy in its cable length estimate. The estimated cable length can be cross verified with the physical length of the cable to determine whether there is deviation in cable characteristics and understand how the PHY may perform as the cable ages.

It's important to note that in single-pair Ethernet applications, cable characteristics differ more widely than in standard Ethernet applications (where CAT5, CAT5e, CAT6 cables are dominantly used). As such, the ALCD measurement information generated by DP83TD510 can be combined with the parameters of a specific cable



model to generate the most accurate cable length estimate. Please refer to DP83TD510 Cable diagnostics App note :SNLA364

#### **SQI (Signal Quality Indicator)**

While TDR can provide information about the existence and location of cable faults, a real time monitor of the link quality can be provide valuable information before a fault occurs. The DP83TD510 provides real time signalto-

noise ratio monitoring to an application.

The cable quality, connector contact, and surrounding environment contribute to the overall channel quality. The Signal Quality Indicator (SQI) can provide insights to the physical connections in an application assembly before it ships, the link quality of a system in noisy environments and immunity testing, or the lifetime trend a of product's health as it ages.

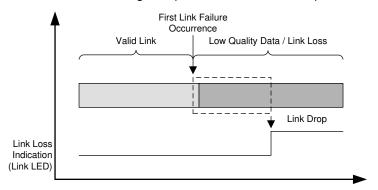
The DP83TD510 monitors link quality by measuring the SNR at periodic intervals whenever an active link is established. The PHY measures the accumulated mean-square error (MSE) in the received signal at the PAM3 slicer from its sliced output level. The signal quality monitoring functions are run automatically in the background of the PHY. Please refer to DP83TD510 Cable diagnostics App note for detail procedure :SNLA364



#### 7.3.12.2 Fast Link Down Functionality

The DP83TD510E includes advanced link-down capabilities that support various real-time applications. The linkdown mechanism is configurable and includes enhanced modes that allow extremely fast link-drop reaction times.

The DP83TD510E supports an enhanced link drop mechanism, also called Fast Link Drop (FLD), which shortens the observation window for determining link. There are multiple ways of determining link status, which can be enabled or disabled based on user preference. Fast Link Drop can be enabled in software using register configuration. FLD can be configured using the Control Register #3 (CR3, address 0x000B). Bits[3:0] and bit[10] allow for various FLD conditions to be enabled. When link drop occurs, indication of a particular fault condition can be read from the Fast Link Down Status Register (FLDS, address 0x000F).



#### Figure 7-9. Fast Link Down

Fast Link Down criteria include:

- RX Error Count when a predefined number of 32 RX\_ERs occur in a 10µs window, the link will be dropped.
- MLT3 Error Count when a predefined number of 20 MLT3 errors occur in a 10µs window, the link will be dropped.
- Low SNR Threshold when a predefined number of 20 threshold crossings occur in a 10µs window, the link will be dropped.
- Signal/Energy Loss when the energy detector indicates energy loss, the link will be dropped.

The Fast Link Down functionality allows the use of each of these options separately or in any combination.

#### Note

Because this mode enables extremely quick reaction time, it is more exposed to temporary bad linkquality scenarios.

### 7.4 Device Functional Modes

DP83TD510E can be used in MII, RMII Maste, RMII Slave and RGMII mode. Refer to RMII section for connection diagram.

#### 7.4.1 Straps Configuration

The DP83TD510E uses many of the functional pins as strap options to place the device into specific modes of operation. The values of these pins are sampled at power up or hard reset. During software resets, the strap options are internally reloaded from the values sampled at power up or hard reset. The strap option pin assignments are defined below. Configuration of the device may be done through the strap pins or through the management register interface. A pullup resistor or a pulldown resistor of suggested values may be used to set the voltage ratio of the strap pin input and the supply to select one of the possible selected modes. The MAC interface pins must support I/O voltages of 3.3 V, 2.5 V, and 1.8 V. As the strap inputs are implemented on these pins, the straps must also support operation at 3.3-V, 2.5-V, and 1.8-V supplies depending on what voltage was selected for I/O. All strap pins have two levels.



PHY offers interal PU or PD resistor for the default strap configuration and eliminates need for external resistor. External resistor for strap is needed only when default configuration needs to be be changed.

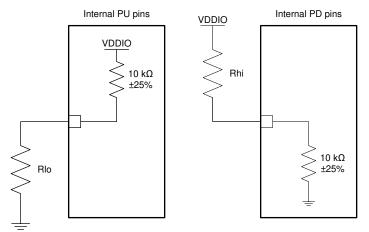


Figure 7-10. Strap Circuit

#### Table 7-5. 2-Level Strap Resistor Ratio

MODE	IDEAL RE	SISTORS
MODE	Rhi (kΩ)	Rio (kΩ)
0	OPEN	2.49
1	2.49	OPEN

#### 7.4.1.1 Straps for PHY Address

	Table 7-6.	PHY	Address	Strap	Table
--	------------	-----	---------	-------	-------

		DEFAULT	PIN #	STRAP NAME	PIN NAME
PHY_ADD0					
0	MODE 0	0	32	Strap9	GPIO1
1	MODE 1				
PHY_ADD1					
0	MODE 0	0	20	Strap6	RX_ERR
1	MODE 1				
PHY_ADD2					
0	MODE 0	0	16	Strap4	RX_D0
1	MODE 1				
PHY_ADD3					
0	MODE 0	0	13	Strap1	RX_D3
1	MODE 1				

Table 7-7. Reach Selection Strap							
PIN NAME	STRAP NAME	PIN #	DEFAULT				
LED_2	Strap7	28	0	0	This Strap defines the voltage level requested by PHY during auto negotiation. It is reflected in bit 12 of 0x20E. While using Force mode for Linkup, the strap controls the output voltage and reflects in bit 12 of 0x18F6 0 : 2.4V & 1-V p2p		
				1	1: 1-V p2p		



Table 7-8. MAC Mode Strap Table	Table 7-8.	MAC Mo	ode Strap	Table
---------------------------------	------------	--------	-----------	-------

PIN NAME	STRAP NAME	PIN #	DEFAULT	Strap8	Strap 3		
	Strap3	15	0	0	0	MII (default)	
RX_D1	Strap5	15	0	0	1	RMII Master	
LED 0	Strap8	29	0	1	0	RGMII	
	Suapo	29		1	1	RMII Slave	

#### Table 7-9. RMII MAC Mode Strap Table

PIN NAME	STRAP NAME	PIN #	DEFAULT		
RX D2	Strap2	14	0	0	CRS_DV/RX_DV Pin 18 is configured as CRS_DV (default)
KX_DZ	Strapz	14	0	1	CRS_DV/RX_DV Pin 18 is configured as RX_DV (For RMII Repeater Mode)

#### Table 7-10. Terminations Selection

PIN NAME	STRAP NAME	PIN #	DEFAULT		
GPIO2	Strap10	8	Mandatory PU/PD	0	Receiver with tapping at 50 $\Omega$ (Recommended)
				1	Receiver tapping at < 40 $\Omega$

#### Table 7-11. Clockout/LED\_1

PIN NAME	STRAP NAME	PIN #	DEFAULT		
RX DV/CRS DV	Strap5	18	0	0	Clockout 25 M( default)
	Stiap5	10	0	1	LED1

#### 7.5 Programming

DP83TD510E provides an IEEE defined register set for programming and status. It also provides an additional register set to configure other features not supported thru IEEE registers.

#### 7.6 MMD Register Address Map

#### Table 7-12. MMD Register Map Address Table

Register Address Range	MMD	Example Usage
0x1000 to 0x18F8	0x1	MMD=0x1, Address=0x08F8
0x3000 to 0x38E7	0x3	MMD=0x3, Address=0x08E7
0x200 to 0x20F	0x7	MMD=07, Address=0x20F
0x0000 to 0x0130, 0x0300-0x0E01	0x1F	MMD=0x1F, Address=0x0000



# 7.7 DP83TD510E Registers

Table 7-13 lists the DP83TD510E registers. All register offset addresses not listed in Table 7-13 should be considered as reserved locations and the register contents should not be modified.

#### DP83TD51010BaseT1L

Address	Acronym Register Name	Section
0x0	MILREG_0	Go
0x2	MILREG_2	Go
0x3	MIL_REG_3	Go
0x10	PHY_STS	Go
0x11	GEN_CFG	Go
0x12	INTERRUPT_REG_1	Go
0x13	INTERRUPT_REG_2	Go
0x15	RX_ERR_CNT	Go
0x16	BISCR	Go
0x17	MAC_CFG_1	Go
0x18	MAC_CFG_2	Go
0x19	SOR_PHYAD	Go
0x1E	TDR_CFG	Go
0x119	PRBS_CFG_1	Go
0x11A	PRBS_CFG_2	Go
0x11B	PRBS_CFG_3	Go
0x11C	PRBS_STATUS_1	Go
0x11D	PRBS_STATUS_2	Go
0x11E	PRBS_STATUS_3	Go
0x11F	PRBS_STATUS_4	Go
0x120	PRBS_STATUS_5	Go
0x121	PRBS_STATUS_6	Go
0x122	PRBS_STATUS_7	Go
0x123	PRBS_CFG_4	Go
0x124	PRBS_CFG_5	Go
0x125	PRBS_CFG_6	Go
0x126	PRBS_CFG_7	Go
0x127	PRBS_CFG_8	Go
0x128	PRBS_CFG_9	Go
0x129	PRBS_CFG_10	Go
0x12A	CRC_STATUS	Go
0x12B	PKT_STAT_1	Go
0x12C	PKT_STAT_2	Go
0x12D	PKT_STAT_3	Go
0x12E	PKT_STAT_4	Go
0x12F	PKT_STAT_5	Go
0x130	PKT_STAT_6	Go
0x200	AN_CONTROL	Go
0x201	AN_STATUS	Go
	AN_ADV_1	Go



#### Table 7-13. DP83TD510E Registers (continued)

Table 7-13. DP831D510E Registers (continued)		
Address	Acronym Register Name	Section
0x203	AN_ADV_2	Go
0x204	AN_ADV_3	Go
0x205	AN_LP_ADV_1	Go
0x206	AN_LP_ADV_2	Go
0x207	AN_LP_ADV_3	Go
0x208	AN_NP_ADV_1	Go
0x209	AN_NP_ADV_2	Go
0x20A	AN_NP_ADV_3	Go
0x20B	AN_LP_NP_ADV_1	Go
0x20C	AN_LP_NP_ADV_2	Go
0x20D	AN_LP_NP_ADV_3	Go
0x20E	AN_CTRL_10BT1	Go
0x20F	AN_STATUS_10BT1	Go
0x300	TDR_CFG1	Go
0x301	TDR_CFG2	Go
0x302	TDR_CFG3	Go
0x303	FAULT_CFG1	Go
0x304	FAULT_CFG2	Go
0x305	FAULT_STAT1	Go
0x306	FAULT_STAT2	Go
0x307	FAULT_STAT3	Go
0x308	FAULT_STAT4	Go
0x309	FAULT_STAT5	Go
0x30A	FAULT_STAT6	Go
0x420	CHIP_SOR_0	Go
0x460	LEDS_CFG_1	Go
0x461	IO_MUX_CFG	Go
0x462	IO_MUX_GPIO_CTRL_1	Go
0x463	IO_MUX_GPIO_CTRL_2	Go
0x467	CHIP_SOR_1	Go
0x468	CHIP_SOR_2	Go
0x469	LEDS_CFG_2	Go
0x60C	AN_STAT_1	Go
0x872	 dsp_reg_72	Go
0x88D	dsp_reg_8d	Go
0x88E	dsp_reg_8e	Go
0x88F	dsp_reg_8f	Go
0x890	dsp_reg_90	Go
0x891	dsp_reg_91	Go
0x892	dsp_reg_92	Go
0x898	dsp_reg_98	Go
		Go
0x899 0x89A 0x89B 0x89B 0x89C	dsp_reg_99 dsp_reg_9a dsp_reg_9b dsp_reg_9c	



### Table 7-13. DP83TD510E Registers (continued)

0x89D         dsp_reg_9d         Go           0x8E9         dsp_reg_e9         Go           0x8EA         dsp_reg_ea         Go           0x8EB         dsp_reg_eb         Go           0x8EC         dsp_reg_ec         Go           0x8ED         dsp_reg_ed         Go           0x8EE         dsp_reg_ea         Go           0x8EE         dsp_reg_ee         Go           0xA9D         alcd_metric         Go           0xA9F         alcd_status         Go           0xA00         PAM_PMD_CTRL_1         Go           0x1000         PAM_PMD_CTRL_2         Go           0x1001         PMA_PMD_CTRL_2         Go           0x1012         PMA_PMD_EXTENDED_ABILITY_2         Go           0x1132         PMA_PMD_CTRL         Go           0x186         PMA_CTRL         Go           0x187         PMA_STATUS         Go           0x187         PMA_STATUS         Go           0x188         TEST_MODE_CTRL         Go           0x386         PCS_CTRL_2         Go           0x386         PCS_CTRL_2         Go	Address	Acronym Register Name	Section
0x8EA         dsp_reg_ea         Go           0x8EB         dsp_reg_eb         Go           0x8EC         dsp_reg_ec         Go           0x8ED         dsp_reg_ed         Go           0x8EE         dsp_reg_ee         Go           0xA9D         alcd_metric         Go           0xA9F         alcd_status         Go           0xA00         PAM_PMD_CTRL_1         Go           0x1000         PAM_PMD_CTRL_2         Go           0x1012         PMA_PMD_EXTENDED_ABILITY_2         Go           0x1848         PMA_CTRL         Go           0x1845         PMA_CTRL         Go           0x1845         PMA_CTRL         Go           0x1845         PMA_CTRL         Go           0x1845         PMA_CTRL         Go           0x1847         PMA_CTRL         Go           0x1846         PMA_CTRL         Go           0x1846         PMA_CTRL         Go           0x3800         PCS	0x89D	dsp_reg_9d	Go
0x8EBdsp_reg_ebGo0x8ECdsp_reg_ecGo0x8EDdsp_reg_edGo0x8EEdsp_reg_eeGo0xA9Dalcd_metricGo0xA9Falcd_statusGo0xE01SCAN_2Go0x1000PAM_PMD_CTRL_1Go0x1007PMA_PMD_CTRL_2Go0x1018PMA_PMD_EXTENDED_ABILITY_2Go0x1844PMA_PMD_CTRLGo0x1857PMA_STATUSGo0x1877PMA_STATUSGo0x1878TEST_MODE_CTRLGo0x3000PCS_CTRLGo0x3866PCS_CTRL_2Go	0x8E9	dsp_reg_e9	Go
0x8ECdsp_reg_ecGo0x8EDdsp_reg_edGo0x8EEdsp_reg_eeGo0xA9Dalcd_metricGo0xA9Falcd_statusGo0xE01SCAN_2Go0x1000PAM_PMD_CTRL_1Go0x1007PMA_PMD_CTRL_2Go0x1018PMA_PMD_EXTENDED_ABILITY_2Go0x1876PMA_CTRLGo0x1877PMA_STATUSGo0x1878TEST_MODE_CTRLGo0x3000PCS_CTRLGo0x3866PCS_CTRL_2Go	0x8EA	dsp_reg_ea	Go
0x8EDdsp_reg_edGo0x8EEdsp_reg_eeGo0xA9Dalcd_metricGo0xA9Falcd_statusGo0xE01SCAN_2Go0x1000PAM_PMD_CTRL_1Go0x1007PMA_PMD_CTRL_2Go0x1008PMA_PMD_EXTENDED_ABILITY_2Go0x1012PMA_PMD_CTRLGo0x1844PMA_CTRLGo0x1875PMA_CTRLGo0x1876PMA_CTRLGo0x1877PMA_STATUSGo0x1884TEST_MODE_CTRLGo0x1875FEST_MODE_CTRLGo0x1876PCS_CTRLGo0x3866PCS_CTRL_2Go	0x8EB	dsp_reg_eb	Go
0x8EEdsp_reg_eeGo0xA9Dalcd_metricGo0xA9Falcd_statusGo0xE01SCAN_2Go0x1000PAM_PMD_CTRL_1Go0x1007PMA_PMD_CTRL_2Go0x1008PMA_PMD_EXTENDED_ABILITY_2Go0x1012PMA_PMD_CTRLGo0x1876PMA_CTRLGo0x1877PMA_STATUSGo0x1878TEST_MODE_CTRLGo0x1876PCS_CTRLGo0x3866PCS_CTRL_2Go	0x8EC	dsp_reg_ec	Go
DXA9Dalcd_metricGo0xA9Falcd_statusGo0xA0Falcd_statusGo0xE01SCAN_2Go0x1000PAM_PMD_CTRL_1Go0x1007PMA_PMD_CTRL_2Go0x1008PMA_PMD_EXTENDED_ABILITY_2Go0x1012PMA_PMD_EXTENDED_ABILITYGo0x1834PMA_PMD_CTRLGo0x1876PMA_CTRLGo0x1877PMA_STATUSGo0x1878TEST_MODE_CTRLGo0x3000PCS_CTRLGo0x3866PCS_CTRL_2Go	0x8ED	dsp_reg_ed	Go
0xA9Falcd_statusGo0xE01SCAN_2Go0x1000PAM_PMD_CTRL_1Go0x1007PMA_PMD_CTRL_2Go0x1008PMA_PMD_EXTENDED_ABILITY_2Go0x1012PMA_PMD_EXTENDED_ABILITYGo0x1834PMA_PMD_CTRLGo0x1876PMA_CTRLGo0x1877PMA_STATUSGo0x1878TEST_MODE_CTRLGo0x3800PCS_CTRLGo0x3866PCS_CTRL_2Go	0x8EE	dsp_reg_ee	Go
0xE01SCAN_2Go0x1000PAM_PMD_CTRL_1Go0x1007PMA_PMD_CTRL_2Go0x1008PMA_PMD_EXTENDED_ABILITY_2Go0x1012PMA_PMD_EXTENDED_ABILITYGo0x1834PMA_PMD_CTRLGo0x1876PMA_CTRLGo0x1877PMA_STATUSGo0x1878TEST_MODE_CTRLGo0x3000PCS_CTRLGo0x3866PCS_CTRL_2Go	0xA9D	alcd_metric	Go
0x1000PAM_PMD_CTRL_1Go0x1007PMA_PMD_CTRL_2Go0x1008PMA_PMD_EXTENDED_ABILITY_2Go0x1012PMA_PMD_EXTENDED_ABILITYGo0x1834PMA_PMD_CTRLGo0x1876PMA_CTRLGo0x18F7PMA_STATUSGo0x18F8TEST_MODE_CTRLGo0x3000PCS_CTRLGo0x38E6PCS_CTRL_2Go	0xA9F	alcd_status	Go
0x1007PMA_PMD_CTRL_2Go0x1008PMA_PMD_EXTENDED_ABILITY_2Go0x1012PMA_PMD_EXTENDED_ABILITYGo0x1834PMA_PMD_CTRLGo0x18F6PMA_CTRLGo0x18F7PMA_STATUSGo0x18F8TEST_MODE_CTRLGo0x3000PCS_CTRLGo0x38E6PCS_CTRL_2Go	0xE01	SCAN_2	Go
0x100BPMA_PMD_EXTENDED_ABILITY_2Go0x1012PMA_PMD_EXTENDED_ABILITYGo0x1834PMA_PMD_CTRLGo0x1856PMA_CTRLGo0x18F7PMA_STATUSGo0x18F8TEST_MODE_CTRLGo0x3000PCS_CTRLGo0x38E6PCS_CTRL_2Go	0x1000	PAM_PMD_CTRL_1	Go
0x1012PMA_PMD_EXTENDED_ABILITYGo0x1834PMA_PMD_CTRLGo0x1856PMA_CTRLGo0x18F7PMA_STATUSGo0x18F8TEST_MODE_CTRLGo0x3000PCS_CTRLGo0x38E6PCS_CTRL_2Go	0x1007	PMA_PMD_CTRL_2	Go
0x1834         PMA_PMD_CTRL         Go           0x18F6         PMA_CTRL         Go           0x18F7         PMA_STATUS         Go           0x18F8         TEST_MODE_CTRL         Go           0x3000         PCS_CTRL         Go           0x38E6         PCS_CTRL_2         Go	0x100B	PMA_PMD_EXTENDED_ABILITY_2	Go
0x18F6         PMA_CTRL         Go           0x18F7         PMA_STATUS         Go           0x18F8         TEST_MODE_CTRL         Go           0x3000         PCS_CTRL         Go           0x38E6         PCS_CTRL_2         Go	0x1012	PMA_PMD_EXTENDED_ABILITY	Go
0x18F7         PMA_STATUS         Go           0x18F8         TEST_MODE_CTRL         Go           0x3000         PCS_CTRL         Go           0x38E6         PCS_CTRL_2         Go	0x1834	PMA_PMD_CTRL	Go
0x18F8         TEST_MODE_CTRL         Go           0x3000         PCS_CTRL         Go           0x38E6         PCS_CTRL_2         Go	0x18F6	PMA_CTRL	Go
0x3000         PCS_CTRL         Go           0x38E6         PCS_CTRL_2         Go	0x18F7	PMA_STATUS	Go
0x38E6 PCS_CTRL_2 Go	0x18F8	TEST_MODE_CTRL	Go
	0x3000	PCS_CTRL	Go
0x38E7 PCS_STATUS Go	0x38E6	PCS_CTRL_2	Go
	0x38E7	PCS_STATUS	Go

Complex bit access types are encoded to fit into small table cells. Table 7-14 shows the codes that are used for access types in this section.

Table 7-14. DP83TD510E Access Type Codes						
Access Type	Code	Description				
Read Type	Read Type					
R	R	Read				
Write Type						
W	W	Write				
WOC	W 0C	Write 0 to clear				
W0S	W 0S	Write 0 to set				
WMC	W	Write				
WSC	W	Write				
Reset or Default Value	Reset or Default Value					
- n		Value after reset or the default value				

## 7.7.1 MII\_REG\_0 Register (Address = 0x0) [Reset = 0x0]

MII\_REG\_0 is shown in Table 7-15.



	Table 7-15. MII_REG_0 Register Field Descriptions							
Bit	Field	Туре	Reset	Description				
15	mii_reset	R/WSC	0x0	1b = Digital in reset and all MII regs (0x0 - 0xF) as well as interrupt status are reset to default 0b = No reset				
14	loopback	R/WMC	0x0	1b = MII loopback 0b = No MII loopback				
13	RESERVED	R	0x0	Reserved				
12	RESERVED	R	0x0	Reserved				
11	power_down	R/WMC	0x0	1b = Power down via register or pin 0b = Normal mode				
10	isolate	R/WMC	0x0	1b = Isolate mode 0b = Normal mode				
9	RESERVED	R	0x0	Reserved				
8	RESERVED	R	0x0	Reserved				
7	RESERVED	R	0x0	Reserved				
6	RESERVED	R	0x0	Reserved				
5	unidirectional_ability	R	0x0	Reserved				
4-0	RESERVED	R	0x0					

## 7.7.2 MII\_REG\_2 Register (Address = 0x2) [Reset = 0x2000]

MII\_REG\_2 is shown in Table 7-16.

Return to the Summary Table.

Table 7-16. MII_REG_2 Register Field Descriptions
---

Bit	Field	Туре	Reset	Description
15-0	oui_21_16	R	0x2000	

## 7.7.3 MII\_REG\_3 Register (Address = 0x3) [Reset = 0x181]

MII\_REG\_3 is shown in Table 7-17.

Return to the Summary Table.

Bit	Field	Туре	Reset	Description
15-10	oui_5_0	R	0x0	
9-5	model_number	R	0xC	Model number
4-0	revision_number	R	0x1	Device revision number

## 7.7.4 PHY\_STS Register (Address = 0x10) [Reset = 0x0]

PHY\_STS is shown in Table 7-18.

Return to the Summary Table.

Bit	Field	Туре	Reset	Description
15-8	RESERVED	R	0x0	
7	mii_interrupt	R/W0C		1b = Interrupt pin had been set 0b = Interrupts pin not set
6-1	RESERVED	R	0x0	

Copyright © 2020 Texas Instruments Incorporated



### Table 7-18. PHY\_STS Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
0	link_status	R	0x0	1b = Link is up 0b = Link is down

## 7.7.5 GEN\_CFG Register (Address = 0x11) [Reset = 0x2A]

GEN\_CFG is shown in Table 7-19.

### Return to the Summary Table.

#### Table 7-19. GEN\_CFG Register Field Descriptions

Bit	Field	Туре	Reset	Description			
15	RESERVED	R	0x0	Reserved			
14	RESERVED	R	0x0	Reserved			
13-12	RESERVED	R	0x0	Reserved			
11	channel_debug_mode	R/W	0x0				
10	debug_mode	R/W	0x0	To reduce simulation time			
9-7	RESERVED	R	0x0				
6-5	tx_fifo_depth	R/W	0x1	Fifo depth for RMII Tx fifo 00b = 4 nibbles 01b = 5 nibbles 10b = 6 nibbles 11b = 8 nibbles			
4	RESERVED	R	0x0				
3	int_polarity	R/W	0x1	1b = Interrupt pin is active low 0b = Interrupt pin active high			
2	force_interrupt	R/W	0x0	Force interrupt pin to be active			
1	int_en	R/W	0x1	1b = Enable interrupt 0b = Disable interrupt			
0	int_oe	R/W	0x0	1b = MDINT_PWDN is interrupt pin 0b = MDINT_PWDN is power down pin			

# 7.7.6 INTERRUPT\_REG\_1 Register (Address = 0x12) [Reset = 0x0]

INTERRUPT\_REG\_1 is shown in Table 7-20.

Return to the Summary Table.

## Table 7-20. INTERRUPT\_REG\_1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	rhf_int	R	0x0	Rx error cnt half full int status Note : Latch high until read
14	RESERVED	R	0x0	
13	link_int	R	0x0	Link status change interrupt status Note : Latch high until clear
12	RESERVED	R	0x0	Reserved
11	esd_int	R	0x0	ESD interrupt status Note : Latch high until clear
10-8	RESERVED	R	0x0	
7	rhf_int_en	R/W	0x0	1b = Enable rx_err_cnt half full interrupt 0b = Disable rx_err_cnt half full interrupt
6	RESERVED	R	0x0	
5	link_int_en	R/W	0x0	1b = Enable link status change interrupt 0b = Disable link status change interrupt



### Table 7-20. INTERRUPT\_REG\_1 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
4	RESERVED	R	0x0	Reserved
3	esd_int_en	R/W		1b = Enable ESD interrupt 0b = Dsiable ESD interrupt
2-0	RESERVED	R	0x0	

### 7.7.7 INTERRUPT\_REG\_2 Register (Address = 0x13) [Reset = 0x0]

INTERRUPT\_REG\_2 is shown in Table 7-21.

Return to the Summary Table.

#### Table 7-21. INTERRUPT\_REG\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-14	RESERVED	R	0x0	
13	page_int	R	0x0	Aneg page received interrupt status Note : Latch high until clear
12-10	RESERVED	R	0x0	
9	pol_int	R	0x0	Polarity change interrupt status Note : Latch high until clear
8	RESERVED	R	0x0	Reserved
7-6	RESERVED	R	0x0	
5	page_int_en	R/W	0x0	1b = Enable aneg page received interrupt 0b = Disable aneg page received interrupt
4-2	RESERVED	R	0x0	
1	pol_int_en	R/W	0x0	1b = Enable polarity change interrupt 0b = Disable polarity change interrupt
0	RESERVED	R/W	0x0	Reserved

## 7.7.8 RX\_ERR\_CNT Register (Address = 0x15) [Reset = 0x0]

RX\_ERR\_CNT is shown in Table 7-22.

Return to the Summary Table.

#### Table 7-22. RX\_ERR\_CNT Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	rx_err_cnt	R	0x0	Counts number of RX_ERR, saturates on max value Note : Clear on read

## 7.7.9 BISCR Register (Address = 0x16) [Reset = 0x100]

BISCR is shown in Table 7-23.

Return to the Summary Table.

#### Table 7-23. BISCR Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-9	RESERVED	R	0x0	
8	core_pwr_mode	R	0x1	1b = Core is in normal power mode 0b = Core is in power down/sleep mode
7	RESERVED	R	0x0	



Bit	Field	Туре	Reset	Description
6-0	loopback_mode	R/W	0x0	0000001b = Reserved 0000010b = PCS loopback (Tx PAM3 to Rx PAM3) 0000100b = Digital loopback 0001000b = Analog loopback 0010000b = Reverse loopback 0100000b = Transmit to MAC in reverse loopback 1000000b = Transmit to MDI in MAC loopback

### Table 7-23. BISCR Register Field Descriptions (continued)

# 7.7.10 MAC\_CFG\_1 Register (Address = 0x17) [Reset = 0x4001]

MAC\_CFG\_1 is shown in Table 7-24.

Return to the Summary Table.

Table 7-24 MAC CEG	1	Register Field Descriptions
	_ '	

Bit	Field	Туре	Reset	Description
15	cfg_rmii_dis_delayed_txd_ en	R/W	0x0	Reserved
14	min_ipg_mode_en	R/W	0x1	
13	cfg_rmii_enh	R/W	0x0	
12	cfg_rgmii_rx_clk_shift_sel	R/W	0x0	1b = RGMII RX clock and data are shifted 0b = RGMII RX clock and data are aligned
11	cfg_rgmii_tx_clk_shift_sel	R/W	0x0	1b = RGMII TX clock and data are shifted 0b = RGMII TX clock and data are aligned
10	RESERVED	R	0x0	
9	cfg_rgmii_en	R/W	0x0	1b = RGMII enable 0b = RGMII disable
8	cfg_rmii_clk_shift_en	R/W	0x0	Reserved
7	cfg_xi_50	R/W	0x0	1b = XI is 50MHz 0b = XI is 25MHz
6	cfg_rmii_slow_mode	R/W	0x0	Setting this bit changes to RMII Master 5MHz mode from RMII Master 50MHz mode
5	cfg_rmii_mode	R/W	0x0	1b = RMII MAC 0b = MII MAC (0x17[9] should be disabled)
4	cfg_rmii_rev1_0	R/W	0x0	1b = RMII rev1.0 (CRS_DV will toggle at the end of a packet to indicate deassertion of CRS)0b = RMII rev1.2 (CRS_DV will remain asserted until final data is transferred. CRS_DV will not toggle at the end of a packet)
3	rmii_ovf_sts	R/W0C	0x0	RMII fifo overflow indication
2	rmii_unf_sts	R/W0C	0x0	RMII fifo underflow indication
1-0	cfg_rmii_elast_buf	R/W	0x1	RMII rx fifo00b = 14 bit tolerance (upto 16800 byte packet)01b = 2 bit tolerance (upto 2400 byte packet)10b = 6 bit tolerance (upto 7200 byte packet)11b = 10 bit tolerance (upto 12000 byte packet)

# 7.7.11 MAC\_CFG\_2 Register (Address = 0x18) [Reset = 0x3]

MAC\_CFG\_2 is shown in Table 7-25.



## Table 7-25. MAC\_CFG\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11	cfg_inv_rx_clk	R/W	0x0	
10	cfg_rmii_crs_dv_sel	R/W	0x0	1b = CRS is sent out on CRS_DV/RXDV for RMII 0b = DV is sent out on CRS_DV/RXDV for RMII
9	rgmii_tx_af_empty_err	R	0x0	
8	rgmii_tx_af_full_err	R	0x0	
7-6	RESERVED	R	0x0	Reserved
5	inv_rgmii_rxd	R/W	0x0	Swap 3:0 to 0:3
4	inv_rgmii_txd	R/W	0x0	Swap 3:0 to 0:3
3	sup_tx_err_fd_rgmii	R/W	0x0	1b = Supress tx_err in full duplex when tx_en not active (CEXT) 0b = Normal
2-0	cfg_rgmii_half_full_th	R/W	0x3	RGMII TX sync FIFO half full threshold. Option to reduce latency for RGMII: If the MAC and PHY are fed by same clock source (no PPM) we can lower the threshold from 2 to 1.

### 7.7.12 SOR\_PHYAD Register (Address = 0x19) [Reset = 0x0]

SOR\_PHYAD is shown in Table 7-26.

Return to the Summary Table.

#### Table 7-26. SOR\_PHYAD Register Field Descriptions

			-	•
Bit	Field	Туре	Reset	Description
15-5	RESERVED	R	0x0	
4-0	SOR_PHYADDR	R	0x0	

## 7.7.13 TDR\_CFG Register (Address = 0x1E) [Reset = 0x0]

TDR\_CFG is shown in Table 7-27.

Return to the Summary Table.

Bit	Field	Туре	Reset	Description
15	tdr_start	R/WMC	0x0	Start TDR procedure. Following additional register configuration are needed. 0x0301 = 0x2403 0x0303 = 0x043E 0x030E = 0x2520 Please refer to Cabl Diagnostics App Note for detailed procedure
14	RESERVED	R	0x0	Reserved
13-2	RESERVED	R	0x0	
1	tdr_done	R	0x0	TDR done indication (only valid once TDR is started)
0	tdr_fail	R	0x0	TDR fail indication

## 7.7.14 PRBS\_CFG\_1 Register (Address = 0x119) [Reset = 0x574]

PRBS\_CFG\_1 is shown in Table 7-28.

Return to the Summary Table.

#### Table 7-28. PRBS\_CFG\_1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-13	RESERVED	R	0x0	



r	Table 7-28. PRBS_CFG_1 Register Field Descriptions (continued)						
Bit	Field	Туре	Reset	Description			
12	send_pkt	R/WMC	0x0	Enables generating MAC packet with fix/incremental data w CRC (pkt_gen_en has to be set and cfg_pkt_gen_prbs has to be clear) Cleared automatically when pkt_done is set			
11	RESERVED	R	0x0				
10-8	cfg_prbs_chk_sel	R/W	0x5	000 : Checker receives from RGMII TX 010 : Checker receives from RMII TX 011 : Checker receives from MII TX 101 : Checker receives from Cu RX			
7	RESERVED	R	0x0				
6-4	cfg_prbs_gen_sel	R/W	0x7	000 : PRBS transmits to RGMII RX 010 : PRBS transmits to RMII RX 011 : PRBS transmits to MII RX 101 : PRBS transmits to Cu TX			
3	cfg_prbs_cnt_mode	R/W	0x0	<ul> <li>1 = Continuous mode, when one of the PRBS counters reaches max value, pulse is generated and counter starts counting from zero again</li> <li>0 = Single mode, When one of the PRBS counters reaches max value, PRBS checker stops counting.</li> </ul>			
2	cfg_prbs_chk_enable	R/W	0x1	Enable PRBS checker xbar (to receive data) To be enabled for rx packet counters to work			
1	cfg_pkt_gen_prbs	R/W	0x0	If set: (1) When pkt_gen_en is set, PRBS packets are generated continuously (3) When pkt_gen_en is cleared, PRBS RX checker is still enabled If cleared: (1) When pkt_gen_en is set, non - PRBS packet is generated (3) When pkt_gen_en is cleared, PRBS RX checker is disabled as well			
0	pkt_gen_en	R/W	0x0	1 = Enable packet/PRBS generator 0 = Disable packet/PRBS generato			

## Table 7-28. PRBS\_CFG\_1 Register Field Descriptions (continued)

## 7.7.15 PRBS\_CFG\_2 Register (Address = 0x11A) [Reset = 0x5DC]

PRBS\_CFG\_2 is shown in Table 7-29.

Return to the Summary Table.

### Table 7-29. PRBS\_CFG\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	cfg_pkt_len_prbs	R/W		Length (in bytes) of PRBS packets . This excludes CRC, Destination and Source address.

## 7.7.16 PRBS\_CFG\_3 Register (Address = 0x11B) [Reset = 0x7D]

PRBS\_CFG\_3 is shown in Table 7-30.

Return to the Summary Table.

#### Table 7-30. PRBS\_CFG\_3 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-13	RESERVED	R	0x0	
12	cfg_prbs_fix_patt_en	R/W	0x0	
11-8	cfg_prbs_fix_patt	R/W	0x0	
7-0	cfg_ipg_len	R/W	0x7D	Inter-packet gap (in bytes) between packets

# 7.7.17 PRBS\_STATUS\_1 Register (Address = 0x11C) [Reset = 0x0]

PRBS\_STATUS\_1 is shown in Table 7-31.

Return to the Summary Table.

### Table 7-31. PRBS\_STATUS\_1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	prbs_byte_cnt	R		Holds number of total bytes that received by the PRBS checker. Value in this register is locked when write is done to register 0x11F bit[0] or bit[1]. When PRBS Count Mode set to zero, count stops on 0xFFFF

## 7.7.18 PRBS\_STATUS\_2 Register (Address = 0x11D) [Reset = 0x0]

PRBS\_STATUS\_2 is shown in Table 7-32.

Return to the Summary Table.

### Table 7-32. PRBS\_STATUS\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	prbs_pkt_cnt_15_0	R		Bits [15:0] of number of total packets received by the PRBS checker Value in this register is locked when write is done to register 0x11F bit[0] or bit[1]. When PRBS Count Mode set to zero, count stops on 0xFFFFFFF

## 7.7.19 PRBS\_STATUS\_3 Register (Address = 0x11E) [Reset = 0x0]

PRBS\_STATUS\_3 is shown in Table 7-33.

Return to the Summary Table.

### Table 7-33. PRBS\_STATUS\_3 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	prbs_pkt_cnt_31_16	R	0x0	Bits [31:16] of number of total packets received by the PRBS checker Value in this register is locked when write is done to register 0x11F bit[0] or bit[1]. When PRBS Count Mode set to zero, count stops on 0xFFFFFFF

## 7.7.20 PRBS\_STATUS\_4 Register (Address = 0x11F) [Reset = 0x0]

PRBS\_STATUS\_4 is shown in Table 7-34.

Return to the Summary Table.

### Table 7-34. PRBS\_STATUS\_4 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-14	RESERVED	R	0x0	
13	prbs_sync_loss	R/W0C	0x0	1b = PRBS has locked 0b = PRBS did not unlock
12	pkt_done	R	0x0	Set when all MAC packets w CRC are transmitted
11	pkt_gen_busy	R	0x0	1 = Packet generator is in process 0 = Packet generator is not in process
10	prbs_pkt_ov	R	0x0	If set, packet counter reached overflow Overflow is cleared when PRBS counters are cleared - done by setting bit #1 of 0x11f



### Table 7-34. PRBS\_STATUS\_4 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
9	prbs_byte_ov	R	0x0	If set, bytes counter reached overflow Overflow is cleared when PRBS counters are cleared - done by setting bit #1 of 0x11f
8	prbs_lock	R	0x0	1 = PRBS checker is locked sync) on received byte stream 0 = PRBS checker is not locked
7-0	prbs_err_cnt	R	0x0	Holds number of errored bits received by the PRBS checker Value in this register is locked when write is done to bit[0] or bit[1] When PRBS Count Mode set to zero, count stops on 0xFF Notes: Writing bit 0 generates a lock signal for the PRBS counters. Writing bit 1 generates a lock and clear signal for the PRBS counters

# 7.7.21 PRBS\_STATUS\_5 Register (Address = 0x120) [Reset = 0x0]

PRBS\_STATUS\_5 is shown in Table 7-35.

Return to the Summary Table.

### Table 7-35. PRBS\_STATUS\_5 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-8	RESERVED	R	0x0	
7-0	prbs_err_ov_cnt	R		Holds number of error counter overflow that received by the PRBS checker. Value in this register is locked when write is done to register 0x11f bit[0] or bit[1]. Counter stops on 0xFF. Note: when PRBS counters work in single mode, overflow counter is not active

## 7.7.22 PRBS\_STATUS\_6 Register (Address = 0x121) [Reset = 0x0]

PRBS\_STATUS\_6 is shown in Table 7-36.

Return to the Summary Table.

### Table 7-36. PRBS\_STATUS\_6 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	pkt_err_cnt_15_0	R		Bits [15:0] of number of total packets with error received by the PRBS checker Value in this register is locked when write is done to register 0x11f bit[0] or bit[1]. When PRBS Count Mode set to zero, count stops on 0xFFFFFFF

## 7.7.23 PRBS\_STATUS\_7 Register (Address = 0x122) [Reset = 0x0]

PRBS\_STATUS\_7 is shown in Table 7-37.

Return to the Summary Table.

### Table 7-37. PRBS\_STATUS\_7 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	pkt_err_cnt_31_16	R		Bits [31:16] of number of total packets with error received by the PRBS checker Value in this register is locked when write is done to register 0x11f bit[0] or bit[1]. When PRBS Count Mode set to zero, count stops on 0xFFFFFFF



# 7.7.24 PRBS\_CFG\_4 Register (Address = 0x123) [Reset = 0x0]

PRBS\_CFG\_4 is shown in Table 7-38.

Return to the Summary Table.

### Table 7-38. PRBS\_CFG\_4 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-8	cfg_pkt_data	R/W	0x0	Fixed data to be sent in Fix data mode
7-6	cfg_pkt_mode	R/W	0x0	2'b00 - Incremental 2'b01 - Fixed 2'b1x - PRBS
5-3	cfg_pattern_vld_bytes	R/W	0x0	Number of bytes of valid pattern in packet (Max - 6)
2-0	cfg_pkt_cnt	R/W	0x0	000b = 1 packet 001b = 10 packets 010b = 100 packets 011b = 1000 packets 100b = 10000 packets 101b = 100000 packets 110b = 1000000 packets 111b = Continuous packets

## 7.7.25 PRBS\_CFG\_5 Register (Address = 0x124) [Reset = 0x0]

PRBS\_CFG\_5 is shown in Table 7-39.

Return to the Summary Table.

#### Table 7-39. PRBS\_CFG\_5 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	pattern_15_0	R/W	0x0	Bits 15:0 of pattern

## 7.7.26 PRBS\_CFG\_6 Register (Address = 0x125) [Reset = 0x0]

PRBS\_CFG\_6 is shown in Table 7-40.

Return to the Summary Table.

```
Table 7-40. PRBS_CFG_6 Register Field Descriptions
```

Bit	Field	Туре	Reset	Description
15-0	pattern_31_16	R/W	0x0	Bits 31:16 of pattern

## 7.7.27 PRBS\_CFG\_7 Register (Address = 0x126) [Reset = 0x0]

PRBS\_CFG\_7 is shown in Table 7-41.

Return to the Summary Table.

### Table 7-41. PRBS\_CFG\_7 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	pattern_47_32	R/W	0x0	Bits 47:32 of pattern

## 7.7.28 PRBS\_CFG\_8 Register (Address = 0x127) [Reset = 0x0]

PRBS\_CFG\_8 is shown in Table 7-42.



### Table 7-42. PRBS\_CFG\_8 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	pmatch_data_15_0	R/W	0x0	Bits 15:0 of Perfect Match Data - used for DA (destination address) match

### 7.7.29 PRBS\_CFG\_9 Register (Address = 0x128) [Reset = 0x0]

PRBS\_CFG\_9 is shown in Table 7-43.

Return to the Summary Table.

#### Table 7-43. PRBS CFG 9 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	pmatch_data_31_16	R/W	0x0	Bits 31:16 of Perfect Match Data - used for DA (destination address) match

### 7.7.30 PRBS\_CFG\_10 Register (Address = 0x129) [Reset = 0x0]

PRBS\_CFG\_10 is shown in Table 7-44.

Return to the Summary Table.

#### Table 7-44. PRBS\_CFG\_10 Register Field Descriptions

-					<u> </u>
	Bit	Field	Туре	Reset	Description
	15-0	pmatch_data_47_32	R/W	0x0	Bits 47:32 of Perfect Match Data - used for DA (destination address) match

## 7.7.31 CRC\_STATUS Register (Address = 0x12A) [Reset = 0x0]

CRC\_STATUS is shown in Table 7-45.

Return to the Summary Table.

#### Table 7-45. CRC\_STATUS Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-2	RESERVED	R	0x0	
1	rx_bad_crc	R	0x0	CRC error indication in packet received on Cu RX
0	tx_bad_crc	R	0x0	CRC error indication in packet transmitted on Cu TX

### 7.7.32 PKT\_STAT\_1 Register (Address = 0x12B) [Reset = 0x0]

PKT\_STAT\_1 is shown in Table 7-46.

Return to the Summary Table.

#### Table 7-46. PKT\_STAT\_1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	tx_pkt_cnt_15_0		0x0	Lower 16 bits of Tx packet counter Note : Register is cleared when 0x12B, 0x12C, 0x12D are read in sequence

## 7.7.33 PKT\_STAT\_2 Register (Address = 0x12C) [Reset = 0x0]

PKT\_STAT\_2 is shown in Table 7-47.



### Table 7-47. PKT\_STAT\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	tx_pkt_cnt_31_16		0x0	Upper 16 bits of Tx packet counter Note : Register is cleared when 0x12B, 0x12C, 0x12D are read in sequence

## 7.7.34 PKT\_STAT\_3 Register (Address = 0x12D) [Reset = 0x0]

PKT\_STAT\_3 is shown in Table 7-48.

Return to the Summary Table.

#### Table 7-48. PKT\_STAT\_3 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	tx_err_pkt_cnt		0x0	Tx packet w error (CRC error) counter Note : Register is cleared when 0x12B, 0x12C, 0x12D are read in sequence

### 7.7.35 PKT\_STAT\_4 Register (Address = 0x12E) [Reset = 0x0]

PKT\_STAT\_4 is shown in Table 7-49.

Return to the Summary Table.

#### Table 7-49. PKT\_STAT\_4 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	rx_pkt_cnt_15_0		0x0	Lower 16 bits of Rx packet counter Note : Register is cleared when 0x12E, 0x12F, 0x130 are read in sequence

## 7.7.36 PKT\_STAT\_5 Register (Address = 0x12F) [Reset = 0x0]

PKT\_STAT\_5 is shown in Table 7-50.

Return to the Summary Table.

### Table 7-50. PKT\_STAT\_5 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	rx_pkt_cnt_31_16		0x0	Upper 16 bits of Rx packet counter Note : Register is cleared when 0x12E, 0x12F, 0x130 are read in sequence

## 7.7.37 PKT\_STAT\_6 Register (Address = 0x130) [Reset = 0x0]

PKT\_STAT\_6 is shown in Table 7-51.

Return to the Summary Table.

#### Table 7-51. PKT\_STAT\_6 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	rx_err_pkt_cnt		0x0	Rx packet w error (CRC error) counter Note : Register is cleared when 0x12E, 0x12F, 0x130 are read in sequence

## 7.7.38 AN\_CONTROL Register (Address = 0x200) [Reset = 0x1000]

AN\_CONTROL is shown in Table 7-52.



Return to the Summary Table.

### Table 7-52. AN\_CONTROL Register Field Descriptions

Bit	Field	Туре	Reset	Description				
15	mr_main_reset	R	0x0	1 = AN reset 0 = AN normal operation Note : Bit is self clearing				
14-13	RESERVED	R	0x0					
12	mr_an_enable	R/W	0x1	1 = enable Auto-Negotiation process 0 = disable Auto-Negotiation process				
11-10	RESERVED	R	0x0					
9	mr_restart_an	R/WSC	0x0	<ul><li>1 = Restart Auto-Negotiation process</li><li>0 = Auto-Negotiation in process, disabled, or not supported</li></ul>				
8-0	RESERVED	R	0x0					

## 7.7.39 AN\_STATUS Register (Address = 0x201) [Reset = 0x8]

AN\_STATUS is shown in Table 7-53.

Return to the Summary Table.

### Table 7-53. AN\_STATUS Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-7	RESERVED	R	0x0	
6	mr_page_received	R/W0C	0x0	1 = A page has been received 0 = A page has not been received
5	mr_an_complete	R	0x0	<ul><li>1 = Auto-Negotiation process completed</li><li>0 = Auto-Negotiation process not completed</li></ul>
4	remote_fault	R/W0C	0x0	<ul><li>1 = remote fault condition detected</li><li>0 = no remote fault condition detected</li></ul>
3	mr_an_ability	R	0x1	<ul><li>1 = PHY is able to perform Auto-Negotiation</li><li>0 = PHY is not able to perform Auto- Negotiation</li></ul>
2	link_status	R/W0S	0x0	1 = Link is up 0 = Link is down
1-0	RESERVED	R	0x0	

# 7.7.40 AN\_ADV\_1 Register (Address = 0x202) [Reset = 0x1]

AN\_ADV\_1 is shown in Table 7-54.

Table 7-54. AN_ADV_1 R	Register Field Descriptions
------------------------	-----------------------------

Bit	Field	Туре	Reset	Description			
15	mr_bp_np_ability	R/W	0x0				
14	mr_bp_ack	R	0x0	Always 0			
13	mr_bp_remote_fault	R/W	0x0				
12-5	mr_bp_12_5	R/W	0x0	Bit 12 - Force Master/Slave Bit 11:10 - Pause Bit 9:5 - Echoes nonce			
4-0	selector_field	R/W	0x1	00001b = IEEE802.3			

# 7.7.41 AN\_ADV\_2 Register (Address = 0x203) [Reset = 0x0]

AN\_ADV\_2 is shown in Table 7-55.

Return to the Summary Table.

### Table 7-55. AN\_ADV\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	mr_bp_31_16	R/W		Bit 20:16 - Transmitted nonce
				Bit 31:21 - A10 to A0

## 7.7.42 AN\_ADV\_3 Register (Address = 0x204) [Reset = 0x0]

AN\_ADV\_3 is shown in Table 7-56.

Return to the Summary Table.

### Table 7-56. AN\_ADV\_3 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	mr_bp_47_32	R/W	0x0	A26 to A11

## 7.7.43 AN\_LP\_ADV\_1 Register (Address = 0x205) [Reset = 0x0]

AN\_LP\_ADV\_1 is shown in Table 7-57.

Return to the Summary Table.

Bit	Field	Туре	Reset	Description
15-0	mr_lp_bp_15_0	R	0x0	LP' base page 15:0

## 7.7.44 AN\_LP\_ADV\_2 Register (Address = 0x206) [Reset = 0x0]

AN\_LP\_ADV\_2 is shown in Table 7-58.

Return to the Summary Table.

```
Table 7-58. AN_LP_ADV_2 Register Field Descriptions
```

Bit	Field	Туре	Reset	Description
15-0	mr_lp_bp_31_16	R	0x0	LP's base page 31:16

## 7.7.45 AN\_LP\_ADV\_3 Register (Address = 0x207) [Reset = 0x0]

AN\_LP\_ADV\_3 is shown in Table 7-59.

Return to the Summary Table.

### Table 7-59. AN\_LP\_ADV\_3 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	mr_lp_bp_47_32	R	0x0	LP's base page 47:32

## 7.7.46 AN\_NP\_ADV\_1 Register (Address = 0x208) [Reset = 0x0]

AN\_NP\_ADV\_1 is shown in Table 7-60.



### Table 7-60. AN\_NP\_ADV\_1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	mr_np_np_ability	R/W	0x0	
14	RESERVED	R	0x0	
13	mr_np_message_page	R/W	0x0	
12	mr_np_ack2	R/W	0x0	
11	mr_np_toggle	R	0x0	
10-0	mr_np_msg_unform_code _field	R/W	0x0	Predefined message codes

## 7.7.47 AN\_NP\_ADV\_2 Register (Address = 0x209) [Reset = 0x0]

AN\_NP\_ADV\_2 is shown in Table 7-61.

Return to the Summary Table.

#### Table 7-61. AN\_NP\_ADV\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	mr_np_unform_code_field _1	R/W	0x0	

## 7.7.48 AN\_NP\_ADV\_3 Register (Address = 0x20A) [Reset = 0x0]

AN\_NP\_ADV\_3 is shown in Table 7-62.

Return to the Summary Table.

#### Table 7-62. AN\_NP\_ADV\_3 Register Field Descriptions

E	Bit	Field	Туре	Reset	Description
1		mr_np_unform_code_field _2	R/W	0x0	

### 7.7.49 AN\_LP\_NP\_ADV\_1 Register (Address = 0x20B) [Reset = 0x0]

AN\_LP\_NP\_ADV\_1 is shown in Table 7-63.

Return to the Summary Table.

### Table 7-63. AN\_LP\_NP\_ADV\_1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	mr_lp_np_np_ability	R	0x0	
14	mr_lp_np_ack	R	0x0	
13	mr_lp_np_message_page	R	0x0	
12	mr_lp_np_ack2	R	0x0	
11	mr_lp_np_toggle	R	0x0	
10-0	mr_lp_np_msg_unform_co de_field	R	0x0	Predefined message codes

### 7.7.50 AN\_LP\_NP\_ADV\_2 Register (Address = 0x20C) [Reset = 0x0]

AN\_LP\_NP\_ADV\_2 is shown in Table 7-64.

Return to the Summary Table.

Copyright  $\ensuremath{\textcircled{C}}$  2020 Texas Instruments Incorporated



### Table 7-64. AN\_LP\_NP\_ADV\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	mr_lp_np_unform_code_fi eld_1	R	0x0	

## 7.7.51 AN\_LP\_NP\_ADV\_3 Register (Address = 0x20D) [Reset = 0x0]

AN\_LP\_NP\_ADV\_3 is shown in Table 7-65.

Return to the Summary Table.

#### Table 7-65. AN LP NP ADV 3 Register Field Descriptions

_					
	Bit	Field	Туре	Reset	Description
	15-0	mr_lp_np_unform_code_fi eld_2	R	0x0	

### 7.7.52 AN\_CTRL\_10BT1 Register (Address = 0x20E) [Reset = 0xA000]

AN\_CTRL\_10BT1 is shown in Table 7-66.

### Return to the Summary Table.

#### Table 7-66. AN\_CTRL\_10BT1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	mr_10bt1_L_capability	R/W	0x1	1 = Advertise PHY as 10BASE-T1L capable 0 = Do not advertise PHY as 10BASE-T1L capable
14	mr_ability_10bt1_L_eee	R/W	0x0	1 = Advertise that the 10BASE-T1L PHY has EEE ability 0 = Do not advertise that the 10BASE-T1L PHY has EEE ability (default)
13	mr_ability_10bt1_L_incr_t x_rx_lvl	R/W	0x1	<ul> <li>1 = Advertise that the 10BASE-T1L PHY has increased transmit/ receive level ability</li> <li>0 = Do not advertise that the 10BASE-T1L PHY has increased transmit/receive level ability (default)</li> </ul>
12	mr_10bt1_L_incr_tx_rx_lvl _rqst	R/W	0x0	1 = Request 10BASE-T1L increased transmit level 0 = Do not request 10BASE-T1L increased transmit level (default)
11-8	RESERVED	R	0x0	
7	RESERVED	R	0x0	Reserved
6	RESERVED	R	0x0	Reserved
5-0	RESERVED	R	0x0	

## 7.7.53 AN\_STATUS\_10BT1 Register (Address = 0x20F) [Reset = 0x0]

AN\_STATUS\_10BT1 is shown in Table 7-67.

Return to the Summary Table.

### Table 7-67. AN\_STATUS\_10BT1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	mr_lp_10bt1_L_capability	R	0x0	1 = Link partner is advertising PHY as 10BASE-T1L capable 0 = Link partner is not advertising PHY as 10BASE-T1L capable
14	mr_lp_ability_10bt1_L_ee e	R	0x0	1 = Link partner is advertising that the 10BASE-T1L PHY has EEE ability 0 = Link partner is not advertising that the 10BASE-T1L PHY has EEE ability



### Table 7-67. AN\_STATUS\_10BT1 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
13	mr_lp_ability_10bt1_L_inc r_tx_rx_lVl	R	0x0	1 = Link partner is advertising that the 10BASE-T1L PHY has increased transmit/ receive level ability 0 = Link partner is not advertising that the 10BASE-T1L PHY has increased transmit/ receive level ability
12	mr_lp_10bt1_L_incr_tx_rx _lvl_rqst	R	0x0	1 = Link partner is requesting 10BASE-T1L link partner increased transmit level 0 = Link partner is not requesting 10BASET1L link partner increased transmit level
11-8	RESERVED	R	0x0	
7	RESERVED	R	0x0	Reserved
6	RESERVED	R	0x0	Reserved
5-0	RESERVED	R	0x0	

# 7.7.54 TDR\_CFG1 Register (Address = 0x300) [Reset = 0x545]

TDR\_CFG1 is shown in Table 7-68.

### Return to the Summary Table.

### Table 7-68. TDR\_CFG1 Register Field Descriptions

			_	<u> </u>
Bit	Field	Туре	Reset	Description
15-13	RESERVED	R	0x0	
12	cfg_tdr_tx_type	R/W	0x0	Transmit voltage level for TDR 0 = 1V 1 = 2.4V
11-8	cfg_forward_shadow_2	R/W	0x5	Forward shadow for segment 2
7-4	cfg_forward_shadow_1	R/W	0x4	Forward shadow for segment 1
3-2	cfg_post_silence_time	R/W	0x1	post TDR silence time
1-0	cfg_pre_silence_time	R/W	0x1	pre TDR silence time

## 7.7.55 TDR\_CFG2 Register (Address = 0x301) [Reset = 0x2404]

TDR\_CFG2 is shown in Table 7-69.

Return to the Summary Table.

### Table 7-69. TDR\_CFG2 Register Field Descriptions

				•
Bit	Field	Туре	Reset	Description
15	RESERVED	R	0x0	
14-8	cfg_end_tap_index_1	R/W	0x24	End tap index for echo coeff sweep for segment 1
7	RESERVED	R	0x0	
6-0	cfg_start_tap_index_1	R/W	0x4	Start tap index for echo coeff sweep for segment 1

## 7.7.56 TDR\_CFG3 Register (Address = 0x302) [Reset = 0x3E80]

TDR\_CFG3 is shown in Table 7-70.

Return to the Summary Table.

### Table 7-70. TDR\_CFG3 Register Field Descriptions

Bit	Field	Туре	Reset	Description			
15-0	cfg_tdr_tx_duration	R/W	0x3E80	TDR transmit duration in usec			

Copyright © 2020 Texas Instruments Incorporated

# 7.7.57 FAULT\_CFG1 Register (Address = 0x303) [Reset = 0x53E]

FAULT\_CFG1 is shown in Table 7-71.

## Return to the Summary Table.

### Table 7-71. FAULT\_CFG1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	RESERVED	R	0x0	
14-8	cfg_tdr_flt_loc_offset_1	R/W	0x5	Tap index offset of dyamic peak equation for segment 1
7-0	cfg_tdr_flt_init_1	R/W	0x3E	Offset of dynamic peak equation for segment 1

## 7.7.58 FAULT\_CFG2 Register (Address = 0x304) [Reset = 0xA]

FAULT\_CFG2 is shown in Table 7-72.

Return to the Summary Table.

### Table 7-72. FAULT\_CFG2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-8	RESERVED	R	0x0	
7-0	cfg_tdr_flt_slope_1	R/W	0xA	Slope of dynamic peak equation (*16 value) for segment 1

## 7.7.59 FAULT\_STAT1 Register (Address = 0x305) [Reset = 0x0]

FAULT\_STAT1 is shown in Table 7-73.

Return to the Summary Table.

### Table 7-73. FAULT\_STAT1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	RESERVED	R	0x0	
14-8	peaks_loc_1	R	0x0	Location of 1st peak
7	RESERVED	R	0x0	
6-0	peaks_loc_0	R	0x0	Location of 1st peak

## 7.7.60 FAULT\_STAT2 Register (Address = 0x306) [Reset = 0x0]

FAULT\_STAT2 is shown in Table 7-74.

Return to the Summary Table.

### Table 7-74. FAULT\_STAT2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	RESERVED	R	0x0	
14-8	peaks_loc_3	R	0x0	Location of 1st peak
7	RESERVED	R	0x0	
6-0	peaks_loc_2	R	0x0	Location of 1st peak

## 7.7.61 FAULT\_STAT3 Register (Address = 0x307) [Reset = 0x0]

FAULT\_STAT3 is shown in Table 7-75.

### Table 7-75. FAULT\_STAT3 Register Field Descriptions

Bit	Bit Field		Reset	Description				
15-8	peaks_amp_0	R	0x0	Amplitude of 1st peak				
7	RESERVED	R	0x0					
6-0	peaks_loc_4	R	0x0	Location of 1st peak				

## 7.7.62 FAULT\_STAT4 Register (Address = 0x308) [Reset = 0x0]

### FAULT\_STAT4 is shown in Table 7-76.

### Return to the Summary Table.

#### Table 7-76. FAULT\_STAT4 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-8	peaks_amp_2	R	0x0	Amplitude of 1st peak
7-0	peaks_amp_1	R	0x0	Amplitude of 1st peak

### 7.7.63 FAULT\_STAT5 Register (Address = 0x309) [Reset = 0x0]

FAULT\_STAT5 is shown in Table 7-77.

Return to the Summary Table.

#### Table 7-77. FAULT\_STAT5 Register Field Descriptions

Bit	Field	Туре	Reset	Description			
15-8	peaks_amp_4	R	0x0	Amplitude of 1st peak			
7-0	peaks_amp_3	R	0x0	Amplitude of 1st peak			

### 7.7.64 FAULT\_STAT6 Register (Address = 0x30A) [Reset = 0x0]

FAULT\_STAT6 is shown in Table 7-78.

### Return to the Summary Table.

#### Table 7-78. FAULT\_STAT6 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-5	RESERVED	R	0x0	
4	peaks_sign_4	R	0x0	Sign of 1st peak
3	peaks_sign_3	R	0x0	Sign of 1st peak
2	peaks_sign_2	R	0x0	Sign of 1st peak
1	peaks_sign_1	R	0x0	Sign of 1st peak
0	peaks_sign_0	R	0x0	Sign of 1st peak

## 7.7.65 CHIP\_SOR\_0 Register (Address = 0x420) [Reset = 0x0]

CHIP\_SOR\_0 is shown in Table 7-79.

Return to the Summary Table.

### Table 7-79. CHIP\_SOR\_0 Register Field Descriptions

Bit	Field	Туре	Reset	Description
6	read_strap_term_sl	R	0x0	Strap Value for for strap on Pin #8
5-0	RESERVED	R	0x0	

Copyright © 2020 Texas Instruments Incorporated



# 7.7.66 LEDS\_CFG\_1 Register (Address = 0x460) [Reset = 0x548]

LEDS\_CFG\_1 is shown in Table 7-80.

Return to the Summary Table.

## Table 7-80. LEDS\_CFG\_1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	RESERVED	R	0x0	Reserved
14	leds_bypass_stretching	R/W	0x0	0 - Noraml Operation 1 - Bypass LEDs stretching
13-12	leds_blink_rate	R/W 0x0		00 = 20Hz (50mSec) 01 = 10Hz (100mSec) 10 = 5Hz (200mSec) 11 = 2Hz (500mSec)
11-8	led_2_option	R/W	0x5	Controlls LED_2 sources (same as bits 3:0)
7-4	led_1_option	R/W	0x4	Controlls LED_1 sources (same as bits 3:0)
3-0	led_0_option	R/W	0x8	Controlls LED_0 source: 0x0 - link OK 0x1 - TX/RX activity 0x2 - TX activity 0x3 - RX activity 0x4 - LR 0x5 - SR 0x6 - LED SPEED : High for 10Base-T 0x7 - Duplex mode 0x8 - link + blink on activity w stretch option 0x9 - blink on activity w stretch option 0xA - blink on tx activity w stretch option 0xA - blink on tx activity w stretch option 0xB - blink on rx activity w stretch option 0xC - link_lost 0xD - PRBS error (toggles on error) 0xE - XMII TX/RX Error with stretch option

# 7.7.67 IO\_MUX\_CFG Register (Address = 0x461) [Reset = 0x5]

IO\_MUX\_CFG is shown in Table 7-81.

Table	7-81.	10	MUX	CFG	Register	Field	Descrip	otions
10010				<b>U</b> . <b>U</b>	110910101	1 1010	000011	

Bit	Field	Туре	Reset	Description	
15	io_oe_n_value	R/W	0x0	when io_oe_n_force_ctrl='1' the direction of all IOs except MDC, MDIO and RESET_N is controlled via this bit: 0 - output 1 - Input	
14	io_oe_n_force_ctrl	R/W	0x0	Debug option - enables forcing the direction of all IOs, except MD0 MDIO and RESET_N. If set, IOs direction is controlled via bit #15	
13-12	pupd_value	R/W	0x0	when pupd_force_cntl='1' the value of the pull up/down is control via this register	
11	pupd_force_cntl	R/W	0x0	when '1' : all the PADs pull up/down is forced via registers	
10-6	RESERVED	R	0x0	Reserved	
5-4	impedance_ctrl	R/W	0x0	MAC interface PAD impedance control bit #0 of this field is the slew control bit. If set to '1', slew rates will be faster (default is 0)	



Bit	Field Type Reset		Reset	Description				
3-2	mac_rx_impedance_ctrl	R/W	0x1	MAC interface PAD impedance control bit #0 of this field is the slew control bit. If set to '1', slew rates will be faster (default is 0)				
1-0	mac_tx_impedance_ctrl	R/W		MAC interface PAD impedance control bit #0 of this field is the slew control bit. If set to '1', slew rates will be faster (default is 0)				

## Table 7-81. IO\_MUX\_CFG Register Field Descriptions (continued)

# 7.7.68 IO\_MUX\_GPIO\_CTRL\_1 Register (Address = 0x462) [Reset = 0x0]

IO\_MUX\_GPIO\_CTRL\_1 is shown in Table 7-82.

Return to the Summary Table.

## Table 7-82. IO\_MUX\_GPIO\_CTRL\_1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	led_2_clk_div_2_en	R/W	0x0	If led_2_gpio is configured to led_2_clk_source, Selects divide by 2 of clock at led_2_clk_source
14-12	led_2_clk_source	R/W	0x0	In case clk_out is MUXed to LED_2 IO, this field controls clk_out source: 0 - XI clock 1 - LD 30MHz clock (Free/recovered based Master/Slave) 2 - 30 MHz ADC clock (recovered) 3 - Free 60MHz clock 4 - 7.5MHz clock (Free/recovered based Master/Slave) 5 - 25MHz clock to PLL (XI or XI/2) 6 - 2.5MHz clock (Free/recovered based Master/Slave)
11	led_2_clk_inv_en	R/W	0x0	If led_2_gpio is configured to led_2_clk_source, Selects inversion of clock at led_2_clk_source
10-8	led_2_gpio_ctrl	R/W	0x0	controls the output of LED_2 IO: 0 - LED_2 1 - Clock out 2 - Interrupt 3 - 1'b0 4 - Reserved 5 -Reserved 6 - constant '0' 7 - constant '1'
7	led_0_clk_div_2_en	R/W	0x0	If led_0_gpio is configured to led_0_clk_source, Selects divide by 2 of clock at led_0_clk_source
6-4	led_0_clk_source	R/W	0x0	In case clk_out is MUXed to LED_0 IO, this field controls clk_out source: 0 - XI clock 1 - LD 30MHz clock (Free/recovered based Master/Slave) 2 - 30 MHz ADC clock (recovered) 3 - Free 60MHz clock 4 - 7.5MHz clock (Free/recovered based Master/Slave) 5 - 25MHz clock to PLL (XI or XI/2) 6 - 2.5MHz clock (Free/recovered based Master/Slave)
3	led_0_clk_inv_en	R/W	0x0	If led_0_gpio is configured to led_0_clk_source, Selects inversion of clock at led_0_clk_source
2-0	led_0_gpio_ctrl	R/W	0x0	controls the output of LED_0 IO: 0 - LED_0 1 - Clock out 2 - Interrupt 3 - 1'b0 4 -Reserved 5 - Reserve 6 - constant '0' 7 - constant '1'



# 7.7.69 IO\_MUX\_GPIO\_CTRL\_2 Register (Address = 0x463) [Reset = 0x0]

IO\_MUX\_GPIO\_CTRL\_2 is shown in Table 7-83.

Return to the Summary Table.

## Table 7-83. IO\_MUX\_GPIO\_CTRL\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-13	gpio_clk_source	R/W	0x0	In case clk_out is MUXed to GPIO IO, this field controls clk_out source: 0 - XI clock 1 - LD 30MHz clock (Free/recovered based Master/Slave) 2 - 30 MHz ADC clock (recovered) 3 - Free 60MHz clock 4 - 7.5MHz clock (Free/recovered based Master/Slave) 5 - 25MHz clock to PLL (XI or XI/2) 6 - 2.5MHz clock (Free/recovered based Master/Slave)
12-10	gpio_ctrl	R/W	0x0	controls the output of GPIO IO: 0 - LED_1 1 - Clock out 2 - Interrupt 3 - 1'b0 4 - Reserved 5 - Reserved 6 - constant '0' 7 - constant '1'
9	cfg_tx_er_on_led2	R/W	0x0	1b = LED_2 is used as TX_ER pin for MII
8	clk_o_clk_div_2_en	R/W	0x0	If clk_out is configured to output clk_o_clk_source, Selects divide by 2 of clock at clk_o_clk_source
7-4	clk_o_clk_source	R/W	0x0	In case clk_out is MUXed to CLK_O IO, this field controls clk_out source: 0 - XI clock 1 - LD 30MHz clock (Free/recovered based Master/Slave) 2 - 30 MHz ADC clock (recovered) 3 - Free 60MHz clock 4 - 7.5MHz clock (Free/recovered based Master/Slave) 5 - 25MHz clock (Free/recovered based Master/Slave) 6 - 2.5MHz clock (Free/recovered based Master/Slave) 8 - CLK25_50 (50 MHz in RMII, 25 MHz in others) 9 - RMII RX 50MHz clock 10 - RMII TX 50MHz clock 11 - MII RX clock 12 - RGMII RX align clock 13 - RGMII RX shift clock
3	clk_o_clk_inv_en	R/W	0x0	If clk_out is configured to output clk_o_clk_source, Selects inversion of clock at clk_o_clk_source
2-0	clk_o_gpio_ctrl	R/W	0x0	controls the output of CLK_O IO: 0 - LED_1 1 - Clock out 2 - Interrupt 3 - 1'b0 4 - Reserved 5 - Reserved 6 - constant '0' 7 - constant '1'

## 7.7.70 CHIP\_SOR\_1 Register (Address = 0x467) [Reset = 0x0]

CHIP\_SOR\_1 is shown in Table 7-84.



### Table 7-84. CHIP\_SOR\_1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-0	sor_15_0	R	0x0	SOR vector, bits [15:0] : SOR[0] - RX_D3 SOR[1] - RX_D2 SOR[2] - RX_D1 SOR[3] - RX_D0 SOR[4] - CLK_OUT/LED_1 SOR[5] - RX_CTRL SOR[6] - RX_ER SOR[7] - LED_2 SOR[8] - LED_0 SOR[9] - GPIO

## 7.7.71 CHIP\_SOR\_2 Register (Address = 0x468) [Reset = 0x0]

CHIP\_SOR\_2 is shown in Table 7-85.

Return to the Summary Table.

## Table 7-85. CHIP\_SOR\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-4	RESERVED	R	0x0	Reserved
3-0	sor_19_16	R	0x0	Reserved

## 7.7.72 LEDS\_CFG\_2 Register (Address = 0x469) [Reset = 0x0]

LEDS\_CFG\_2 is shown in Table 7-86.

Return to the Summary Table.

## Table 7-86. LEDS\_CFG\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-11	RESERVED	R	0x0	Reserved
10	led_2_polarity	R/W	0x0	LED_2 polarity: 0 - Active low 1 - Active high
9	led_2_drv_val	R/W	0x0	If bit #8 is set, this is the value of LED_2
8	led_2_drv_en	R/W	0x0	0 - LED_2 is in normal operation mode 1 - Drive the value of LED_2 (driven value is bit 9)
7	RESERVED	R	0x0	Reserved
6	led_1_polarity	R/W	0x0	LED_1 polarity: 0 - Active low 1 - Active high
5	led_1_drv_val	R/W	0x0	If bit #4 is set, this is the value of LED_1
4	led_1_drv_en	R/W	0x0	0 - LED_1 is in normal operation mode 1 - Drive the value of LED_1 (driven value is bit #5)
3	RESERVED	R	0x0	Reserved
2	led_0_polarity	R/W	0x0	LED_0 polarity: 0 - Active low 1 - Active high
1	led_0_drv_val	R/W	0x0	If bit #1 is set, this is the value of LED_1
0	led_0_drv_en	R/W	0x0	0 - LED_0 is in normal operation mode 1 - Drive the value of LED_0 (driven value is bit #1)

# 7.7.73 AN\_STAT\_1 Register (Address = 0x60C) [Reset = 0x0]

AN\_STAT\_1 is shown in Table 7-87.

# Return to the Summary Table.

### Table 7-87. AN\_STAT\_1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	master_slave_resol_fail	R	0x0	1b = Master SLave resolution failed 0b = Master Slave resolution successful
14-12	an_state	R	0x0	
11	RESERVED	R	0x0	
10-8	hd_state	R	0x0	
7	RESERVED	R	0x0	
6-4	rx_state	R	0x0	
3-0	an_tx_state	R	0x0	

## 7.7.74 dsp\_reg\_72 Register (Address = 0x872) [Reset = 0x0]

dsp\_reg\_72 is shown in Table 7-88.

Return to the Summary Table.

### Table 7-88. dsp\_reg\_72 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-10	RESERVED	R	0x0	
9-0	mse_sqi	R	0x0	SQI : Reciever Avg Mean Square Value

## 7.7.75 dsp\_reg\_8d Register (Address = 0x88D) [Reset = 0x14]

dsp\_reg\_8d is shown in Table 7-89.

## Return to the Summary Table.

### Table 7-89. dsp\_reg\_8d Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11-0	cfg_alcd_2p4_metric_step 1	R/W	0x14	ALCD reference metric for 0m for 2p4V mode

## 7.7.76 dsp\_reg\_8e Register (Address = 0x88E) [Reset = 0x1D]

dsp\_reg\_8e is shown in Table 7-90.

Return to the Summary Table.

### Table 7-90. dsp\_reg\_8e Register Field Descriptions

E	Bit	Field	Туре	Reset	Description
15	5-12	RESERVED	R	0x0	
1		cfg_alcd_2p4_metric_step 2	R/W	0x1D	ALCD reference metric for 200m for 2p4V mode

# 7.7.77 dsp\_reg\_8f Register (Address = 0x88F) [Reset = 0x24]

dsp\_reg\_8f is shown in Table 7-91.



Return to the Summary Table.

Table 7-91. dsp	_reg_8f Re	egister Field	Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11-0	cfg_alcd_2p4_metric_step 3	R/W	0x24	ALCD reference metric for 400m for 2p4V mode

### 7.7.78 dsp\_reg\_90 Register (Address = 0x890) [Reset = 0x35]

dsp\_reg\_90 is shown in Table 7-92.

Return to the Summary Table.

#### Table 7-92. dsp\_reg\_90 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11-0	cfg_alcd_2p4_metric_step 4	R/W	0x35	ALCD reference metric for 600m for 2p4V mode

## 7.7.79 dsp\_reg\_91 Register (Address = 0x891) [Reset = 0x43]

dsp\_reg\_91 is shown in Table 7-93.

Return to the Summary Table.

#### Table 7-93. dsp\_reg\_91 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11-0	cfg_alcd_2p4_metric_step 5	R/W	0x43	ALCD reference metric for 800m for 2p4V mode

### 7.7.80 dsp\_reg\_92 Register (Address = 0x892) [Reset = 0x60]

dsp\_reg\_92 is shown in Table 7-94.

Return to the Summary Table.

#### Table 7-94. dsp\_reg\_92 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11-0	cfg_alcd_2p4_metric_step 6	R/W	0x60	ALCD reference metric for 1000m for 2p4V mode

### 7.7.81 dsp\_reg\_98 Register (Address = 0x898) [Reset = 0x2E]

dsp\_reg\_98 is shown in Table 7-95.

Return to the Summary Table.

Table 7-95. dsp_reg_98 Register Field Descriptions	Table 7-95. dsp re	g 98 Register Field	Descriptions
--	--------------------	---------------------	--------------

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11-0	cfg_alcd_1p0_metric_step 1	R/W	0x2E	ALCD reference metric for 0m for 1p0V mode

Copyright © 2020 Texas Instruments Incorporated

# 7.7.82 dsp\_reg\_99 Register (Address = 0x899) [Reset = 0x41]

dsp\_reg\_99 is shown in Table 7-96.

## Return to the Summary Table.

### Table 7-96. dsp\_reg\_99 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11-0	cfg_alcd_1p0_metric_step 2	R/W	0x41	ALCD reference metric for 200m for 1p0V mode

## 7.7.83 dsp\_reg\_9a Register (Address = 0x89A) [Reset = 0x58]

dsp\_reg\_9a is shown in Table 7-97.

Return to the Summary Table.

#### Table 7-97. dsp\_reg\_9a Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
	cfg_alcd_1p0_metric_step 3	R/W	0x58	ALCD reference metric for 400m for 1p0V mode

## 7.7.84 dsp\_reg\_9b Register (Address = 0x89B) [Reset = 0x89]

dsp\_reg\_9b is shown in Table 7-98.

Return to the Summary Table.

### Table 7-98. dsp\_reg\_9b Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11-0	cfg_alcd_1p0_metric_step 4	R/W	0x89	ALCD reference metric for 600m for 1p0V mode

## 7.7.85 dsp\_reg\_9c Register (Address = 0x89C) [Reset = 0xB2]

dsp\_reg\_9c is shown in Table 7-99.

Return to the Summary Table.

#### Table 7-99. dsp\_reg\_9c Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11-0	cfg_alcd_1p0_metric_step 5	R/W	0xB2	ALCD reference metric for 800m for 1p0V mode

## 7.7.86 dsp\_reg\_9d Register (Address = 0x89D) [Reset = 0x107]

dsp\_reg\_9d is shown in Table 7-100.

Return to the Summary Table.

#### Table 7-100. dsp\_reg\_9d Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	



Table 7-100. dsp\_reg\_9d Register Field Descriptions (continued)

	Bit	Field	Туре	Reset	Description
	11-0	cfg_alcd_1p0_metric_step 6	R/W	0x107	ALCD reference metric for 1000m for 1p0V mode

### 7.7.87 dsp\_reg\_e9 Register (Address = 0x8E9) [Reset = 0x0]

dsp\_reg\_e9 is shown in Table 7-101.

Return to the Summary Table.

#### Table 7-101. dsp\_reg\_e9 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-8	RESERVED	R	0x0	
7-0	cfg_alcd_cable_0	R/W	0x0	

### 7.7.88 dsp\_reg\_ea Register (Address = 0x8EA) [Reset = 0x19]

dsp\_reg\_ea is shown in Table 7-102.

Return to the Summary Table.

#### Table 7-102. dsp\_reg\_ea Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-8	RESERVED	R	0x0	
7-0	cfg_alcd_cable_1	R/W	0x19	

### 7.7.89 dsp\_reg\_eb Register (Address = 0x8EB) [Reset = 0x2F]

dsp\_reg\_eb is shown in Table 7-103.

Return to the Summary Table.

#### Table 7-103. dsp\_reg\_eb Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-8	RESERVED	R	0x0	
7-0	cfg_alcd_cable_2	R/W	0x2F	

### 7.7.90 dsp\_reg\_ec Register (Address = 0x8EC) [Reset = 0x51]

dsp\_reg\_ec is shown in Table 7-104.

Return to the Summary Table.

#### Table 7-104. dsp\_reg\_ec Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-8	RESERVED	R	0x0	
7-0	cfg_alcd_cable_3	R/W	0x51	

## 7.7.91 dsp\_reg\_ed Register (Address = 0x8ED) [Reset = 0x64]

dsp\_reg\_ed is shown in Table 7-105.

Return to the Summary Table.

Copyright © 2020 Texas Instruments Incorporated



#### Table 7-105. dsp\_reg\_ed Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-8	RESERVED	R	0x0	
7-0	cfg_alcd_cable_4	R/W	0x64	

### 7.7.92 dsp\_reg\_ee Register (Address = 0x8EE) [Reset = 0x7A]

dsp\_reg\_ee is shown in Table 7-106.

### Return to the Summary Table.

### Table 7-106. dsp\_reg\_ee Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-8	RESERVED	R	0x0	
7-0	cfg_alcd_cable_5	R/W	0x7A	

### 7.7.93 alcd\_metric Register (Address = 0xA9D) [Reset = 0x0]

alcd\_metric is shown in Table 7-107.

Return to the Summary Table.

### Table 7-107. alcd\_metric Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-4	ALCD_Metric_Value	R	0x0	
3-0	RESERVED	R	0x0	Reserved

## 7.7.94 alcd\_status Register (Address = 0xA9F) [Reset = 0x0]

alcd\_status is shown in Table 7-108.

### Return to the Summary Table.

### Table 7-108. alcd\_status Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	ALCD_Complete	R	0x0	0 : In progress 1 : Complete
14-11	RESERVED	R	0x0	Reserved
10-0	ALCD_Cable_Length	R	0x0	In meters

## 7.7.95 SCAN\_2 Register (Address = 0xE01) [Reset = 0x10]

SCAN\_2 is shown in Table 7-109.

Return to the Summary Table.

#### Table 7-109. SCAN\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-9	RESERVED	R	0x0	
8-4	scan_state_saf	R	0x1	
3	cfg_en_efuse_burn	R	0x0	Enable the switch in the power supply path for EFUSE module Note : This bit written by programming 0x0303 in 0x0E00
2-0	RESERVED	R	0x0	



## 7.7.96 PAM\_PMD\_CTRL\_1 Register (Address = 0x1000) [Reset = 0x0]

PAM\_PMD\_CTRL\_1 is shown in Table 7-110.

Return to the Summary Table.

### Table 7-110. PAM\_PMD\_CTRL\_1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	PMA_Reset	R	0x0	1b = PMA/PMD reset         0b = Normal operation         Note : Read write bit, self clearing         Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1         from [15:12] while using the address. Please remove 0x1 from         [15:12] while using the address.
14-12	RESERVED	R	0x0	
11	cfg_low_power	R	0x0	1b = Low-power mode0b = Normal operationNote : Read write bitPrefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1from [15:12] while using the address.
10-1	RESERVED	R	0x0	
0	PMA_loopback	R	0x0	1 = Enable loopback mode 0 = Disable loopback mode Note : Read write bit Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address. Please remove 0x1 from [15:12] while using the address.

## 7.7.97 PMA\_PMD\_CTRL\_2 Register (Address = 0x1007) [Reset = 0x3D]

PMA\_PMD\_CTRL\_2 is shown in Table 7-111.

Return to the Summary Table.

### Table 7-111. PMA\_PMD\_CTRL\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-6	RESERVED	R	0x0	
5-0	cfg_pma_type_selection	R		111101b = BASE-T1 type selection for device Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address. Please remove 0x1 from [15:12] while using the address.

### 7.7.98 PMA\_PMD\_EXTENDED\_ABILITY\_2 Register (Address = 0x100B) [Reset = 0x800]

PMA\_PMD\_EXTENDED\_ABILITY\_2 is shown in Table 7-112.

Return to the Summary Table.

#### Table 7-112. PMA\_PMD\_EXTENDED\_ABILITY\_2 Register Field Descriptions

			_	
Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11	base_t1_extended_abilitie s	R	0x1	1b = PMA/PMD has BASE-T1 extended abilities listed in register 1.18 0b = PMA/PMD does not have BASE-T1 extended abilities Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address.
10-0	RESERVED	R	0x0	

# 7.7.99 PMA\_PMD\_EXTENDED\_ABILITY Register (Address = 0x1012) [Reset = 0x4]

PMA\_PMD\_EXTENDED\_ABILITY is shown in Table 7-113.

Return to the Summary Table.

### Table 7-113. PMA\_PMD\_EXTENDED\_ABILITY Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-4	RESERVED	R	0x0	
3	RESERVED	R	0x0	Reserved
2	mr_10_base_t1I_ability	R	0x1	1b = PMA/PMD is able to perform 10BASE-T1L 0b = PMA/PMD is not able to perform 10BASE-T1L Prefixed 0x1 in [15:12] of address to differentiate.Please remove 0x1 from [15:12] while using the address.
1	RESERVED	R	0x0	Reserved
0	RESERVED	R	0x0	Reserved

## 7.7.100 PMA\_PMD\_CTRL Register (Address = 0x1834) [Reset = 0x4002]

PMA\_PMD\_CTRL is shown in Table 7-114.

Return to the Summary Table.

### Table 7-114. PMA\_PMD\_CTRL Register Field Descriptions

			-	
Bit	Field	Туре	Reset	Description
15	RESERVED	R	0x0	
14	cfg_master_slave_val	R/W	0x1	1b = Configure PHY as MASTER 0b = Configure PHY as SLAVE Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address.
13-4	RESERVED	R	0x0	
3-0	cfg_type_selection	R	0x2	0000b = Reserved 0001b = Reserved 0010b = 10BASE-T1L 0011b = Reserved 01xxb = Reserved 1xxxb = Reserved Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address.

## 7.7.101 PMA\_CTRL Register (Address = 0x18F6) [Reset = 0x0]

PMA\_CTRL is shown in Table 7-115.

Return to the Summary Table.

## Table 7-115. PMA\_CTRL Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	PMA_Reset	R	0x0	1 = PMA reset 0 = Normal operation Note : Read write bit, self clearing Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address.
14	cfg_transmit_disable	R	0x0	1 = Transmit disable 0 = Normal operation Note : Read write bit Prefixed 0x1 in [15:12] of address to differentiate.Please remove 0x1 from [15:12] while using the address.
13	RESERVED	R	0x0	



## Table 7-115. PMA\_CTRL Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
12	cfg_incr_tx_lvl	R/W	0x0	1 = Enable 2.4 Vpp operating mode 0 = Enable 1.0 Vpp operating mode Prefixed 0x1 in [15:12] of address to differentiate.Please remove 0x1 from [15:12] while using the address.
11	cfg_low_power	R	0x0	1 = Low-power mode 0 = Normal operation Note : Read write bit Prefixed 0x1 in [15:12] of address to differentiate.Please remove 0x1 from [15:12] while using the address.
10	cfg_eee_enable	R/W	0x0	1 = Enable EEE mode 0 = Disable EEE mode Prefixed 0x1 in [15:12] of address to differentiate.Please remove 0x1 from [15:12] while using the address.
9-1	RESERVED	R	0x0	
0	PMA_loopback	R	0x0	1 = Enable loopback mode 0 = Disable loopback mode Note : Read write bit Prefixed 0x1 in [15:12] of address to differentiate.Please remove 0x1 from [15:12] while using the address.

# 7.7.102 PMA\_STATUS Register (Address = 0x18F7) [Reset = 0x3000]

PMA\_STATUS is shown in Table 7-116.

Table 7-116 PMA	STATUS Registe	r Field Descriptions
	JIAIUJ NEUISIE	

Bit	Field	Туре	Reset	Description	
15-14	RESERVED	R	0x0		
13	loopback_ability	R	0x1 1 = PHY has loopback ability 0 = PHY has no loopback ability Prefixed 0x1 in [15:12] of address to differentiate. Please rer from [15:12] while using the address.		
12	tx_lvl_incr_ability	R	0x1 1 = PHY has 2.4 Vpp operating mode ability 0 = PHY does not have 2.4 Vpp operating mode ability Prefixed 0x1 in [15:12] of address to differentiate. Please remove from [15:12] while using the address.		
11	low_power_ability	R	0x0	1 = PMA has low-power ability 0 = PMA does not have low-power ability Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address.	
10	eee_ability	R	0x0	1 = PHY has EEE ability 0 = PHY does not have EEE ability Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address.	
9	receive_fault_ability	R	0x0	1 = PMA has the ability to detect a fault condition on the receive path 0 = PMA does not have the ability to detect a fault condition on the receive path Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address.	
8-3	RESERVED	R	0x0		
2	receive_polarity	R	0x0	1 = Receive polarity is reversed 0 = Receive polarity is not reversed Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address.	



	Table 7-110. FMA_STATOS Register Field Descriptions (continued)				
Bit	Field	Туре	Reset	Description	
1	receive_fault	R/W0C	0x0	1 = Fault condition detected 0 = Fault condition not detected Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address.	
0	receive_link_status	R/W0S	0x0	1 = PMA receive link up 0 = PMA receive link down Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address.	

# Table 7-116. PMA\_STATUS Register Field Descriptions (continued)

# 7.7.103 TEST\_MODE\_CTRL Register (Address = 0x18F8) [Reset = 0x0]

TEST\_MODE\_CTRL is shown in Table 7-117.

Return to the Summary Table.

## Table 7-117. TEST\_MODE\_CTRL Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-13	cfg_test_mode	R/W	0x0	1xxb = Reserved 011b = Test mode 3 010b = Test mode 2 001b = Test mode 1 000b = Normal (non-test) operation Prefixed 0x1 in [15:12] of address to differentiate. Please remove 0x1 from [15:12] while using the address.
12-0	RESERVED	R	0x0	

# 7.7.104 PCS\_CTRL Register (Address = 0x3000) [Reset = 0x0]

PCS\_CTRL is shown in Table 7-118.

## Return to the Summary Table.

## Table 7-118. PCS\_CTRL Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	PCS_Reset	R	0x0	1 = PCS reset 0 = Normal operation Note - RW bit, self clear bit Prefixed 0x3 in [15:12] of address to differentiate. Please remove 0x3 from [15:12] while using the address.
14	mmd3_loopback	R	0x0	1 = Enable loopback mode 0 = Disable loopback mode Note - RW bit Prefixed 0x3 in [15:12] of address to differentiate. Please remove 0x3 from [15:12] while using the address.
13-0	RESERVED	R	0x0	

# 7.7.105 PCS\_CTRL\_2 Register (Address = 0x38E6) [Reset = 0x0]

PCS\_CTRL\_2 is shown in Table 7-119.



### Table 7-119. PCS\_CTRL\_2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
15	PCS_Reset	R	0x0	1 = PCS reset 0 = Normal operation Note - RW bit, self clear bit Prefixed 0x3 in [15:12] of address to differentiate. Please remove 0x3 from [15:12] while using the address.
14	mmd3_loopback	R	0x0	1 = Enable loopback mode 0 = Disable loopback mode Note - RW bit Prefixed 0x3 in [15:12] of address to differentiate. Please remove 0x3 from [15:12] while using the address.
13-0	RESERVED	R	0x0	

# 7.7.106 PCS\_STATUS Register (Address = 0x38E7) [Reset = 0x0]

PCS\_STATUS is shown in Table 7-120.

Return to the Summary Table.

## Table 7-120. PCS\_STATUS Register Field Descriptions

Bit	Field	Туре	Reset	Description
15-12	RESERVED	R	0x0	
11	tx_lpi_received	R/W0C	0x0 1 = Tx PCS has received LPI 0 = LPI not received Prefixed 0x3 in [15:12] of address to differentiate. Please refrom [15:12] while using the address.	
10	rx_lpi_received	R/W0C	0x0 1 = Rx PCS has received LPI 0 = LPI not received Prefixed 0x3 in [15:12] of address to differentiate. Please ren from [15:12] while using the address.	
9	tx_lpi_indication	R	0x0	1 = Tx PCS is currently receiving LPI 0 = PCS is not currently receiving LPI Prefixed 0x3 in [15:12] of address to differentiate. Please remove 0x3 from [15:12] while using the address.
8	rx_lpi_indication	R	0x0	1 = Rx PCS is currently receiving LPI 0 = PCS is not currently receiving LPI Prefixed 0x3 in [15:12] of address to differentiate. Please remove 0x3 from [15:12] while using the address.
7	fault	R/W0C	0x0	1 = Fault condition detected 0 = No fault condition detected Prefixed 0x3 in [15:12] of address to differentiate. Please remove 0x3 from [15:12] while using the address.
6-3	RESERVED	R	0x0	
2	receive_link_status	R/W0S	0x0	1 = PCS receive link up 0 = PCS receive link down Prefixed 0x3 in [15:12] of address to differentiate. Please remove 0x3 from [15:12] while using the address.
1-0	RESERVED	R	0x0	



# 8 Application and Implementation

Note

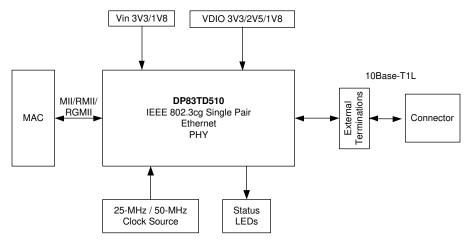
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

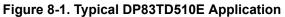
## 8.1 Application Information

When using the device for Ethernet applications, it is necessary to meet certain requirements for normal operation. The following subsections are intended to assist in appropriate component selection and required circuit connections.

## **8.2 Typical Applications**

Figure 8-1 shows a typical application for the DP83TD510E.







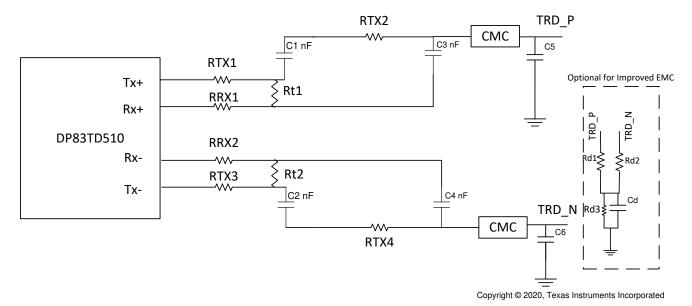
### 8.2.1 Termination Circuit

DP83TD510E is expected to be used in Intrinsic Safe and non Intrinsic Safe Applications. Please refer to appropriate termination circuit based on the application needs. Termination circuit and passive values may need to be adapted according to application needs. Please refer to "Extend network reach with IEEE 802.3cg 10BASET1L Ethernet PHYs" for details.

### **Related information**

https://www.ti.com/lit/an/sluaaa9/sluaaa9.pdf

# 8.2.1.1 Termination Circuit for Intrinsic Safe Applications



## Figure 8-2. Termination Circuit for Intrinsic Safe Applications

#### Table 8-1. Termination Circuit Component Value for Intrinsic Safe Applications

	Applications	1v p2p Intrinsic Safe Config 1	1v p2p Intrinsic Safe Config 2
1	RTX1, RTX3	26.5	50
2	RTX2, RTX4 (Ω)	23.5	0
3	RRX1, RRX2 (Ω)	2К	2K
4	Rt1(Ω)	NC	0
5	Rt2(Ω)	NC	0
6	Rd1(Ω)	1К	1K
7	Rd2(Ω)	1К	1K
8	Rd3(Ω)	160K	160K
9	C1	230 nF	230 nF
10	C2	230 nF	230 nF
11	C3	5 nF	NC
12	C4	5 nF	NC
13	C5	100 pF < C < 400 pF ( default: 100 pF	100 pF < C < 400 pF ( default: 100 pF
14	C6	100 pF < C < 400 pF ( default: 100 pF	100 pF < C < 400 pF ( default: 100 pF
15	Cd	0.01 uF	0.01 uF



Please ensure over all impedance on the Transmitter shall be  $50\Omega$ . If additional components on path adding the impedance, it shall be compensated by reducing Rtx1/Rtx3.

Incase Applications requires Rtx2/Rtx4 as non zero and Rt1/Rt2 0 ohms are used, this will cause reciever to recieve attenuated signal. Please check the need for enabling strap10 on GPIO2.

### 8.2.1.2 Components Range for Power Coupling/Decoupling

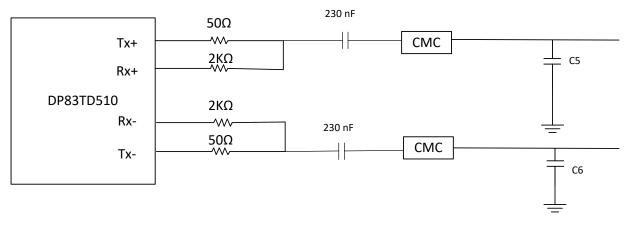
Below table provides recommended component ranges for Power/Data decoupling network

#### Table 8-2. Recommended Components Range for Power Coupling/Decoupling

	Components	Range
1	Cap of ESD diode between MDI lines (Surge protection)	< 100 pF ( Differential Cap)
2	Cap of TVS Diode (MDI line to ground)*	< 75 pF
3	Cap of Clamping Diodes (parallel to power coupling inductor)	< 50 pF
4	Power coupling inductor	<ul> <li>Inductance 500 uH &lt; L &lt;1.5 mH,</li> <li>DC Resistance &lt; 200 mΩ</li> </ul>
5	Cap of Rectifier Diodes	<50 pF

### 8.2.1.3 Termination Circuit for Non-Intrinsic Safe Applications

Following termination circuit is recommended for application in non intrinsic safe application like in Building Automation, Factory Automation etc



Copyright © 2020, Texas Instruments Incorporated

## Figure 8-3. Termination Circuit for Non-Intrinsic Safe Applications

### 8.2.1.4 CMC Specifications

Table 8-3. CMC Specifications

Parameters	Range
Inductance	450 uH - 2.2 mH
Leakage Inductance	< 500 nH
DC Resistance	< 200 mΩ

### 8.2.2 Design Requirements

The design requirements for the DP83TD510E are:

1. AVD Supply = 3.3 V

2. VDDIO Supply = 3.3 V or 1.8 V



3. Reference Clock Input = 25 MHz or 50 MHz (RMII Slave)

#### 8.2.2.1 Clock Requirements

The DP83TD510E supports an external CMOS-level oscillator source or an internal oscillator with an external crystal.

### 8.2.2.1.1 Oscillator

If an external clock source is used, XI should be tied to the clock source and XO should be left floating. The amplitude of the oscillator should be a nominal voltage of VDDIO.

#### 8.2.2.1.2 Crystal

The use of a 25-MHz, parallel resonant, 20-pF load crystal is recommended if operating with a crystal. A typical connection diagram is shown below for a crystal resonator circuit. The load capacitor values will vary with the crystal vendors; check with the vendor for the recommended loads.

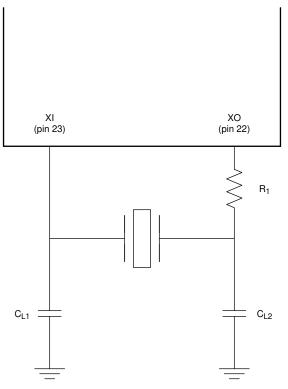


Figure 8-4. Crystal Oscillator Circuit

Table 8-4.	25-MHz	Crystal \$	Specification
	20 101112	Jotar	opeenioutien

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Frequency			25		MHz
Frequency Tolerance	Including all parameters (Temperature, aging etc)	-50		50	ppm
Load Capacitance			15	30	pF
ESR			50	150	Ohm



## 9 Power Supply Recommendations

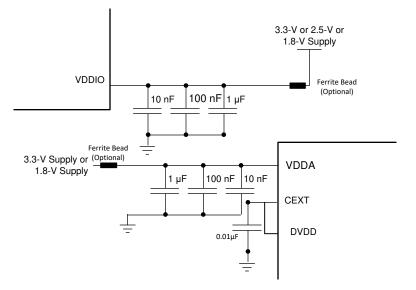
The DP83TD510E is capable of operating from Single Supply 3V3. It supports single supply operations from 1V8 for Short Reach (1v p2p) mode. It also supports Dual Supply Operations for Lowest Power Dissipation. It also supports VDDIO to work at 3.3-V, 2.5-V or 1.8-V supply voltages PHY has capability to detect the power supply levels automatically for both AVDD and VDDIO.

Single Power Supply Operations : Analog supply shall be powered by 3.3 V or 1.8 V. AVDD of 3V3 can support both Long Reach ( 2.4-v p2p) and Short Reach( 1-v p2p).

Please note with AVDD 1.8 V, only Short Cable mode of 1-V p2p will be supported.

Appropriate straps shall be configured to ensure Auto Negotiation transmits the correct capabilities of the PHY.

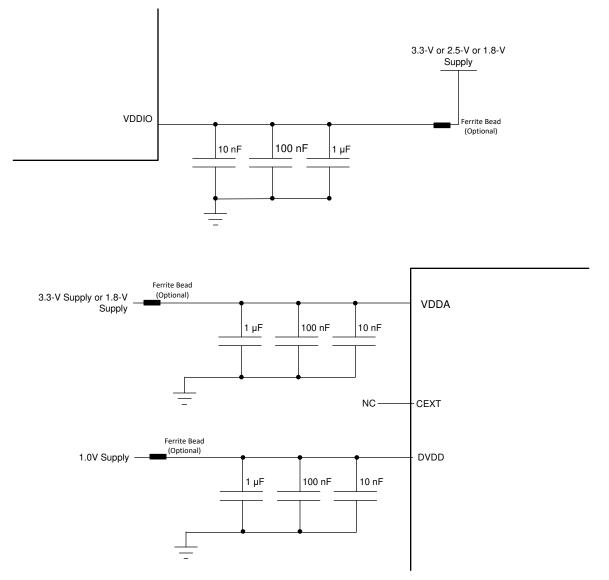
The recommended power supply de-coupling network is shown below:



### Figure 9-1. DP83TD510E Single Power Supply Decoupling Recommendation

For Dual Supply Operations, digital voltage rail of 1.0 V externally shall be supplied seperately. This help reduce the power consumption further of the DP83TD510E. See below connections for Dual Power Supply.





### Figure 9-2. DP83TD510E Dual Supply Power Supply Decoupling Recommendation



## 10 Layout 10.1 Layout Guidelines 10.1.1 Signal Traces

PCB traces are lossy and long traces can degrade signal quality. Keep traces as short as possible. Unless mentioned otherwise, all signal traces must be  $50-\Omega$  single-ended impedance. Differential traces must  $100-\Omega$  differential. Take care to ensure impedance is controlled throughout. Impedance discontinuities cause reflections leading to emissions and signal integrity issues. Stubs should be avoided on all signal traces, especially differential signal pairs.

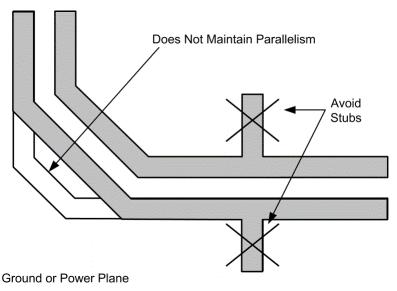


Figure 10-1. Differential Signal Traces

Within the differential pairs, trace lengths should be run parallel to each other and matched in length. Matched lengths minimize delay differences, avoiding an increase in common mode noise and emissions. Length matching is also important for MAC interface connections. All RMII transmit signal traces should be length matched to each other and all RMII receive signal traces should be length matched to each other.

Ideally, there should be no crossover or vias on signal path traces. Vias present impedance discontinuities and should be minimized when possible. Route trace pairs on the same layer. Signals on different layers should not cross each other without at least one return path plane between them. Differential pairs should always have a constant coupling distance between them. For convenience and efficiency, TI recommends routing critical signals first (that is, MDI differential pairs, reference clock, and MAC IF traces).



#### 10.1.2 Return Path

A general best practice is to have a solid return path beneath all MDI signal traces. This return path can be a continuous ground or DC power plane. Reducing the width of the return path can potentially affect the impedance of the signal trace. This effect is more prominent when the width of the return path is comparable to the width of the signal trace. Breaks in return path between the signal traces should be avoided at all cost. A signal crossing a split plane may cause unpredictable return path currents and could impact signal quality and result in emissions issues.

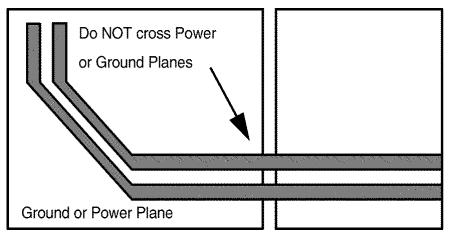


Figure 10-2. Differential Signal Pair and Plane Crossing



### 10.1.3 Metal Pour

All metal pours that are not signals or power must be tied to ground. There must be no floating metal in the system, and there must be no metal between differential traces.

### 10.1.4 PCB Layer Stacking

To meet signal integrity and performance requirements, a minimum four-layer PCB is recommended. However, a six-layer PCB should be used when possible.

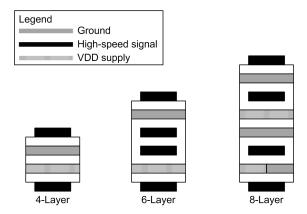


Figure 10-3. Recommended Layer Stack-Up

### 10.2 Layout Example

Please refer DP83TD510E EVM for information regarding layout.



## **11 Device and Documentation Support**

### **11.1 Device Support**

### **11.2 Support Resources**

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

### 11.3 Trademarks

TI E2E<sup>™</sup> is a trademark of Texas Instruments.

All trademarks are the property of their respective owners.

#### **11.4 Electrostatic Discharge Caution**



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 11.5 Glossary

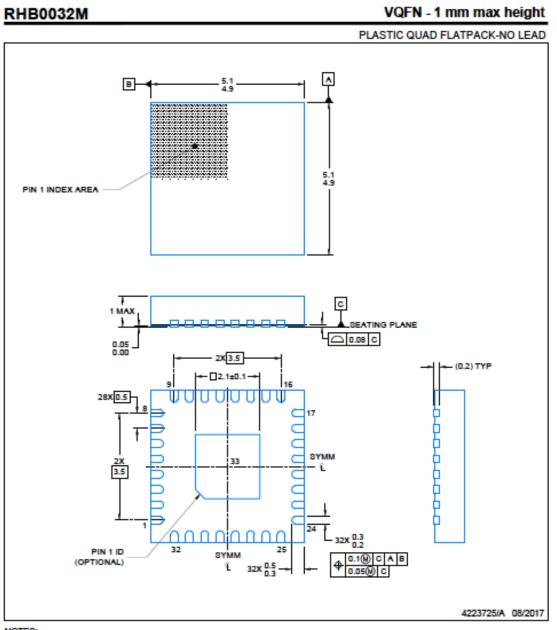
TI Glossary This glossary lists and explains terms, acronyms, and definitions.



PACKAGE OUTLINE

## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



NOTES:

- All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M
- per ASME Y14.5M. 2. This drawing is subject to change without notice.

3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.

Figure 12-1. DP83TD510E Package Drawing

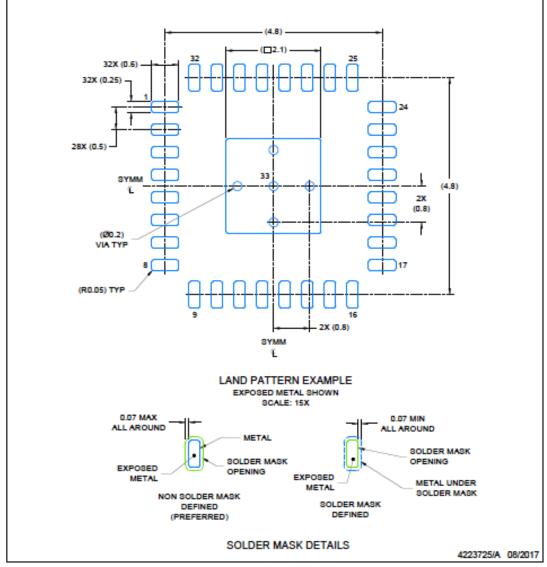


### EXAMPLE BOARD LAYOUT

VQFN - 1 mm max height

RHB0032M

PLASTIC QUAD FLATPACK-NO LEAD



NOTES: (continued)

 This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments Iterature number SLUA271 (www.tl.com/lt/slua271).

 Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

Figure 12-2. DP83TD510E Package Drawing

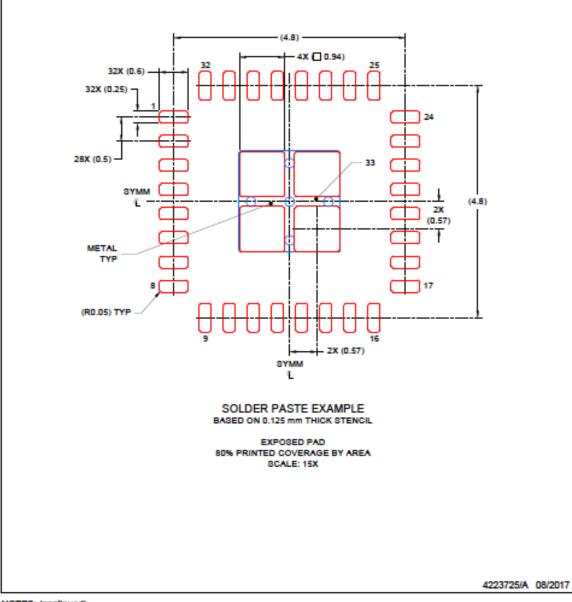


## EXAMPLE STENCIL DESIGN

### VQFN - 1 mm max height

RHB0032M

PLASTIC QUAD FLATPACK-NO LEAD



NOTES: (continued)

 Laser cutting apertures with trapezoidal wails and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

Figure 12-3. DP83TD510E Package Drawing



## PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
DP83TD510ERHBR	ACTIVE	VQFN	RHB	32	3000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 105	510E	Samples
DP83TD510ERHBT	ACTIVE	VQFN	RHB	32	250	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 105	510E	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW**: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



www.ti.com

# PACKAGE OPTION ADDENDUM

10-Apr-2023



Texas

STRUMENTS

## TAPE AND REEL INFORMATION





#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal												
Device	-	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DP83TD510ERHBR	VQFN	RHB	32	3000	330.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
DP83TD510ERHBT	VQFN	RHB	32	250	180.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2



www.ti.com

# PACKAGE MATERIALS INFORMATION

3-Jun-2022



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DP83TD510ERHBR	VQFN	RHB	32	3000	367.0	367.0	35.0
DP83TD510ERHBT	VQFN	RHB	32	250	210.0	185.0	35.0

# **RHB 32**

5 x 5, 0.5 mm pitch

# **GENERIC PACKAGE VIEW**

## VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.

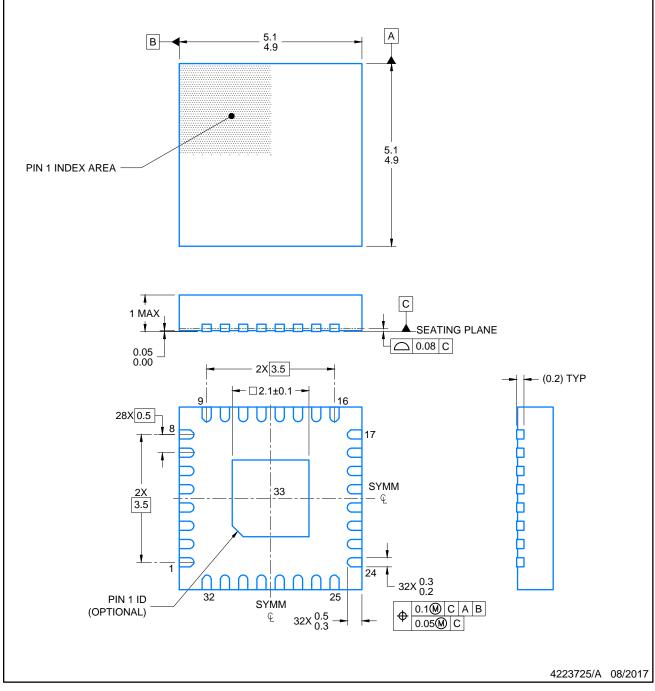


# **RHB0032M**

# **PACKAGE OUTLINE**

## VQFN - 1 mm max height

PLASTIC QUAD FLATPACK-NO LEAD



NOTES:

- All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing 1. per ASME Y14.5M.
- 2.
- This drawing is subject to change without notice. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance. 3.

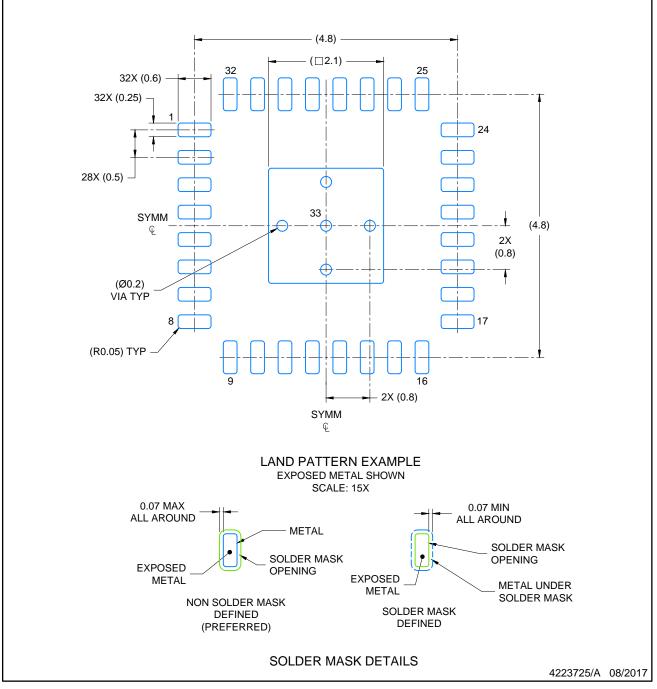


## **RHB0032M**

## **EXAMPLE BOARD LAYOUT**

## VQFN - 1 mm max height

PLASTIC QUAD FLATPACK-NO LEAD



NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

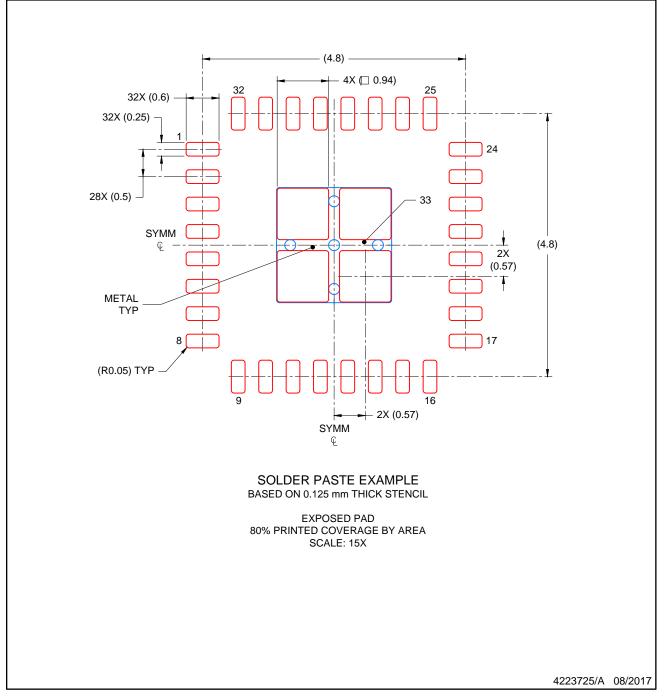


## **RHB0032M**

## **EXAMPLE STENCIL DESIGN**

## VQFN - 1 mm max height

PLASTIC QUAD FLATPACK-NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



## IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2023, Texas Instruments Incorporated